

University of Bologna

Dipartimento di Informatica – Scienza e Ingegneria (DISI)

Engineering Bologna Campus

Class of Infrastructures for Cloud **Computing and Big Data M**

CORBA, C/S and Events, Multicast, MOM

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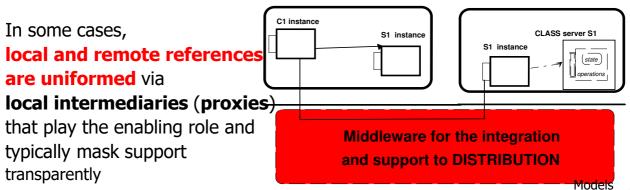
C/S MW and more

REMOTE REFERENCES

In many local environments (in object-oriented system), we need the capacity of referring to some external resources, in order to coordinate different machines (virtual or physical)

A C1 on one node must refer to a remote instance, the same as if they were local instances on the same node

To refer to a remote instance we need some **intermediary** support that extends the visibility to remote nodes



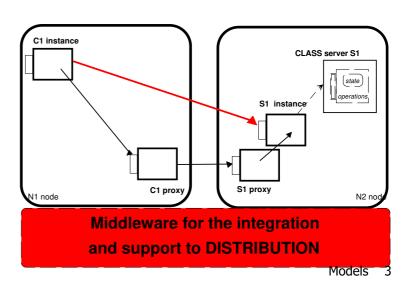
RMI REMOTE REFERENCES

Between two JAVA JVM systems, we can use Java Remote Method Invocation (RMI) that build two proxies

- -one from the customer (stub)
- -one on the side of the servant (skeleton)

Such proxies are often **generated automatically** and make the user part reasoning regardless of the specific deployments

Similarly other environments (**CORBA**, **DCOM**, etc.) define their specific support for OO cases



REMOTE REFERENCES via PROXY

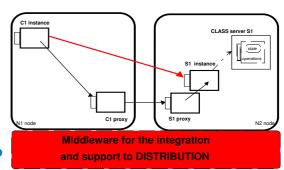
Two Java virtual machines can use **PROXIES to get remote** visibility of object references

RMI support many solutions but proposes problems:

- How do you get the reference to the server? (name system)
- Where are the ancillary classes?
- How to obtain them (while running)?
- And if there are any inconsistencies?
- And if the server is not active?
- And if you don't keep the status?

About **remote references**:

- two references to the same object?
- two references for the same service?



REMOTE REFERENCES & MIDDLEWARE

A central point in all middlewares that abstract away and hide details from users for remote access is how to enable and manage a remote reference in all its aspects A remote reference allows access to non-local entity must surely be transparently

But costs must be considered and evaluated for each aspects of the support mechanism

- How does the remote reference cost?
- How is the cost of middleware to support organization?
- How to obtain remote references?
- Are inconsistencies possible?
- What are the responsibilities of the middleware? ...

REMOTE Serve state Client Middleware to support **EASY TRANSPARENT DISTRIBUTION**

Models 5

INTERMEDIARIES & PROXIES

PROXY

In a communication we may have intermediaries placed and deployed either side, the client and the service provider

PROXY

from client or from server

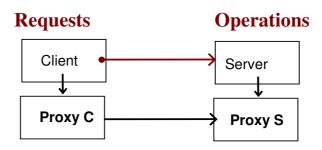
proxy

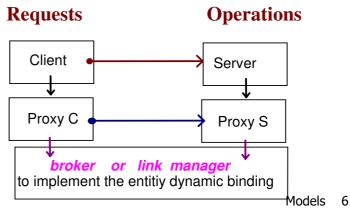
C/S stub & skeleton interceptor

to add functions

broker

something similar to a container





MIDDLEWARE: CORBA as a C/S MW

OMG- Object Management Group

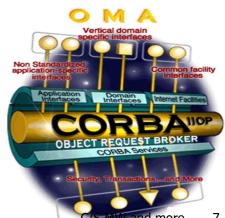
CORBA started in 1989 with **440 company** Microsoft, Digital, HP, NCR, SUN, OSF, etc. with main objective to create a use and management system of a distributed architecture

Common Object Request Broker Architecture **CORBA standard** v1 ⇒ 1991, v1.2 ⇒ 1992

v2 ⇒ 1996, v3 ⇒ 2000

Orbix SunOS Solaris, Iris, Windows NT, HP/UX, AIX, OSF/1, ÚnixWare **DSOM** IBM

General specification of an Object (component) Middleware to use in heterogeneous distribute systems not tied to a specific language



MIDDLEWARE: CORBA

STANDARD OPEN SYSTEM based on OBJECT models with heterogeneous components to implement mutual and complete interaction and integration components, between such inside distributed environments also objects oriented (C/S model) **CORBA** requires:

- definition of a language as service interface
- definition and support to objects interaction
- integration bus for different environments objects (ORB)
- interaction between systems with different managers
- different deployment languages (language mapping)

The objective is to allow services support without posing limits on user application lifecycle

CORBA ARCHITECTURE

Common Object Request Broker Architecture CORBA, as a common environment, Object Management Architecture, for multi-architecture and multi-language scenarios, with an optimal integration with legacy systems and best support for differentiated projects for server and clients

Object Request Broker (ORB) is the heart of the architecture and acts as a broker of communication, to allow both static and dynamic links (!?) between entities

ORB behave as an always available enabler and allows:

- control of allocation and visibility of objects
- control of methods and of communication
- control of accessory services always available inside OMA for every language mapping
- simplified management of every possible services

CORBA is middleware to support an infinite lifetime for applications

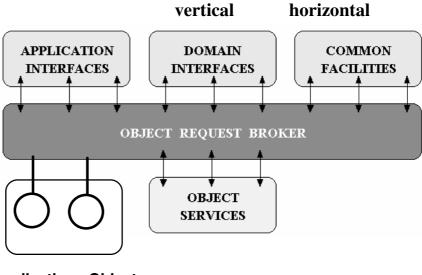
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9

CORBA as a BUS

ORB is the center of Object Management Architecture ORB as a bus center of an architecture that aims at the integration among every resources of an organization

Every managed application objects can belong to different environments and must be able to mutually communicate without any need of redesign



Applications Object

Object Management Architecture

Other additional environment components

Common Facilities CF (horizontal)

Set of specific features

User Interface (client-site),

System Management, Information, Task (server-site)

Domain Interfaces DI (vertical)

Features dedicated to application areas, for ex. manufacturing, telecommunications, electronic commerce, transportation, business objects, healthcare, finance, life science, ...

Application Interfaces

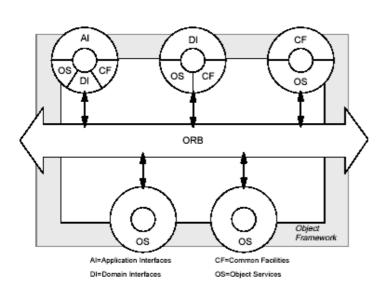
Non standard in any way and application-dependent

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11

Object Management Architecture - OMA

Ambiente Object Framework





Object Management Architecture

Every component can connect to every other one, preparing link either before or during execution (if unknown before), using the service of one or more ORB (known dynamically)

Set of additional environment components

Object Services or CORBA Services (Common Mw Services)

Some operations are basic for object

- naming and trading service (compatible with OO)
- event and notification service (less Object-Oriented)

In addition to further operations (or services)

For lifecycle management, relational, transactional, concurrency control, security, ...

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13

CORBA COMPONENTS

The essential components of OMA architecture, i.e., CORBA, associated to an ORB:

- Object Request Broker (ORB)

- Interface Definition Language (IDL)

- Basic Object Adapter (e POA ...) (BOA e POA)

- Static Invocation Interface (SII)

- **Dynamic Invocation Interface** (DII)

- Interface e Impl. Repository (IR e IMR)

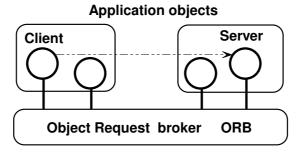
- Integration Protocols (GIOP)

Those components are at very different level

ORB CONTINUOUS SUPPORT

Object Request Broker (ORB) must coordinate invocation of local and remote services (dynamically)

- Identify implementation of an abject as a servant to requests (object location)
- prepare the servant to receive the request via adapter (object creation, activation & management)
- transfer the request from the client to the servant
- return **reply** to client

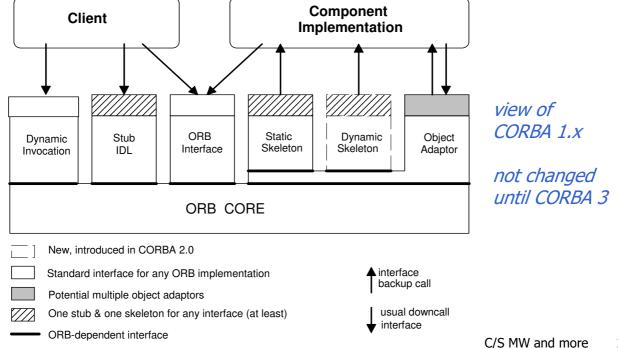


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15

CORBA: DYNAMIC VISION

Elements in action: overall user view



COMMON LANGUAGE in CORBA

Interface Definition Language (CORBA IDL) must identify and coordinate requested and offered services, local and remote (for either static or dynamic interactions)

- Both servants and clients can identify themselves to make themselves mutually known
- Both operations request and service offers can be optimally associated
- CORBA reuse the experience from already developed and available IDLs for defining a general multi-language IDL

Unfortunately IDL prescribe predetermined identification and link and statically recognized (CORBA static binding)

And if we want bindings unknown at development time?

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17

CORBA IDL for MULTILANGUAGE

Interface Definition Language (CORBA IDL) coordinates requested and offered services identification, with different languages

```
interface Factory //OMG IDL
{
    Object create(); // CORBA object or reference
};
```

This interface permits to refer an object of type Factory (IDL) and to request the **create** operation (without **in** or **out** parameters) that returns a generic CORBA object (type Object, that is a reference to the object of interface Object)

IDL makes possible to define **new interfaces and new** general **types** and **abstract**, by need, to make them available and registered, and eventually concretely usable inside different language environments

CORBA does **not** provide any **object creation** (neither Factory): the creation is inside language environments and predefined there, outside CORBA scopes (the same as C does not provide any I/O)

CORBA IDL → STUB E SKELETON

The Interface Definition Language (CORBA IDL) allows to generate support component (stub and skeleton), for communication and data, inside different languages

The **stub** enable working on the *message from the client* perspective (marshalling) and acting as client proxy

The **skeleton** collaborate with the ORB *accepting service request* and adapting it to the server (unmarshalling), by managing requests and responses

DEPLOYMENT

Typically, there is a **static link** between *interface* - *client* - *servant* (not between **client** and **servant**, but between **client** - **service** and **service** - **servant**)

The **objects inside their different language environments** are bound to the stub and skeleton before execution (stub and skeleton are objects? no)

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19

CORBA ADAPTER

Adapter (Object Adapter) system component to overcome inhomogeneity and differences among implementation of different service environments of different servants

(the Adapter does not connect with data presentation)

The Adapter is on the **server** side, with typical tasks of:

- object registration functions
- object external reference generation
- object and internal process activation even on demand
- requests demultiplexing to uncouple them
- send requests (upcall) to registered objects

Firsts adapters were Basic (BOA), then Portable (POA)

(OA are also CORBA objects? no, as OA are pseudo-objects)

INTERFACE REPOSITORY in CORBA

Interface Repository allows to know details about every IDL data type and to explore interfaces, exported from existent objects and available during execution

The interfaces are translated to different programming languages (static binding) where components are defined and compiled (language mapping)

IR allows to know and manage available interfaces dynamically and to decide at runtime (dynamic binding) what is available and convenient

Allows overcoming static approach: for example for a *gateway* that allows access to CORBA interfaces of an environment and cannot be recompiled for every new interface

IR service description system (it is not a naming system)
(IR is an object? yes)

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21

ORB and IR in CORBA

In CORBA, ORB is the middle enabler of any (remote) execution and operation request between different entities

Every request **is always delivered** via the ORB and then server-side mediated BY the adapter

The ORB do not know about any **type information**, that are outside his scope and contained inside stub, skeleton and **language environment**

Interface Repository works as a dynamic catalogue of interfaces (not necessarily for static stub and skeleton),

And it is present for **dynamic explorations** at runtime, if it is necessary to retrieve information on dynamic interfaces

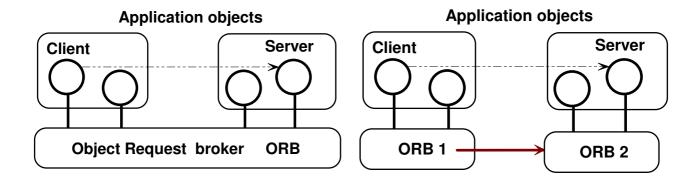
The interfaces must be always registered within the IR at their time of use and before consultation

In the **static case**, the IR is generally not needed (its function is plaid by proxies)

DIFFERENT ORB SYSTEMS

ORB for communication of objects (intra-ORB) and also for communication between objects in different ORBs (inter-ORB)

In one CORBA system or in more CORBA systems managing different brokers



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23

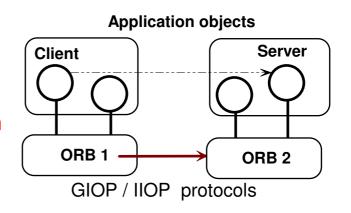
DIFFERENT CORBA SYSTEMS

Definition of Inter-ORB standards to establish how to integrate different CORBA systems without problems

Necessity of standard protocols **ORB-to-ORB interoperability G**eneral **I**nter-**O**RB **P**rotocol (**GIOP**) that prescribe a standard message format

CORBA specifies a protocol between different ORBs in terms of architecture and data exchange

Binary Communication protocol: data are optimized and non user-readable (no source) Common Data Representation (CDR) standard



INTER-ORB PROTOCOL: GIOP e IIOP

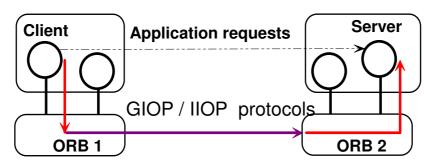
Definition (since version 2) of Inter-ORB Protocols to precisely the interaction between different CORBA systems

ORB interoperability protocol

General Inter-ORB Protocol (GIOP) - Binary protocol

Common specification of data representation, data format, interaction with transport messages (semantic assumptions: reliable, connection, ...)

for Internet using TCP/IP - Internet Inter-ORB Protocol (IIOP)

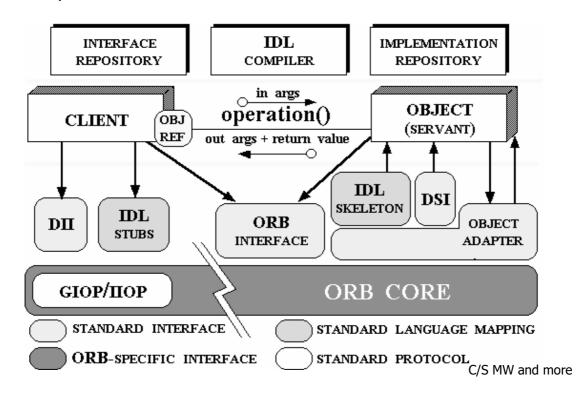


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25

CORBA ARCHITECTURE

Overall picture of a communication between ORBs



CORBA: PSEUDO-OBJECTS

Support components and pseudo-objects

Stub generated from IDL interface for a specific language Skeleton generated from IDL interface for a specific language

These components realize the Static Invocation Interface SII

The SII consists also of other architecture component, such as **IDL interfaces** (to generate stub and skeleton), (interface and implementation) **repositories** to find component specifications and implementation, and **object references**

The dynamic part is implemented in other pseudo-objects

DII, **D**ynamic Invocation Interface, or *Request* object introduced for client dynamic invocation

DSI, **D**ynamic **S**keleton **I**nterface, or *ServerRequest* object introduced for server dynamic invocation

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27

ORB base functions

ORB acts as a coordinator, as an enabler, and as a manager of services available on the system

CORBA applications produces **objects** that become part of the system beyond **application lifetime**

The **applications** and the **objects** are developed using **different environments** to represent **stable resources** that can act to request **methods** and **execute operations**

ORB intermediates any interaction and

- coordinates requests from client objects, transparently from the position and the implementation of remote objects
- facilitates and manages communication through the use of references to existing servant objects
- supports and controls the whole interaction

ORB functions

ORB is a fully object interaction enabler, by suggesting a default blocking synchronous interaction

ORB limits its interaction responsibility by delegating individual language environments for final execution CORBA is not responsible for object creation and moving CORBA employs external remote references that are externally created by language implementation environments that must define their service objects (servant)

CORBA obtains remote references via:

- conversion of **string references** and vice versa (objects referred and translated into strings stringification, and vice versa)
- use of objects directory, by using name services (Trading e Naming service)
- Passing of reference parameters to servants

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29

CORBA IDL

INTERFACE DEFINITION LANGUAGE (OMG IDL) has been introduced to grant flexibility over heterogeneous platforms

IDL are declarative languages to specify interfaces and involved data (for API parameters)

Many common IDL are procedural

- * OSI ASN.1 / GMDO
- * ONC **XDR** (SUN RPC)
- * Microsoft IDL

CORBA IDL is an **object-oriented** language (*derived from C++*)

Obviously, different IDLs are **not compatible** with each other, even if often are different only for **syntax** and **identification systems** and **entity names**

CORBA IDL

CORBA IDL is a purely description language for data and method interfaces

- description of interfaces definition
- interfaces as sets of method and attributes
- · multiple inheritance of interfaces
- exception definition
- automatic management of attributes
- mapping for different languages and environments

The compiler can obtain automatically stubs for clients/servants even using different languages

We must consider different language mapping for references to servant objects (in different languages)

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31

CORBA IDL EXAMPLE

```
module Stock
{exception Invalid_Stock {}; exception Invalid_Index {};
  const length = 100;

interface Quoter {
   attribute float quote; readonly attribute float quotation;
   long get_quote(in string stock_name) raises (Invalid_Stock);
  };
  interface SpecialQuoter: Quoter {
   attribute float quotehistory [length];
   readonly int index [length];
   long get_next (in string stock_name) raises (Invalid_Index);
   long get_first(in string stock_name) raises (Invalid_Index);
  };
  interface CancelQuoter: SpecialQuoter {
   long cancelhistory (out float cancelledquote [length])
  };
}
```

CORBA IDL SUPPORT

For any attribute, an automatic access function is provided suited for permitted operations

(_get for readings and _set for writings)

```
attribute float quote;
float _get_quote ();
void _set_quote (in float q);
readonly attribute ind index;
float _get_index ();
```

For any exception, the state (completion_status) provides information on behavior semantics

```
COMPLETED_YES,
COMPLETED_NO,
COMPLETED_MAYBE
```

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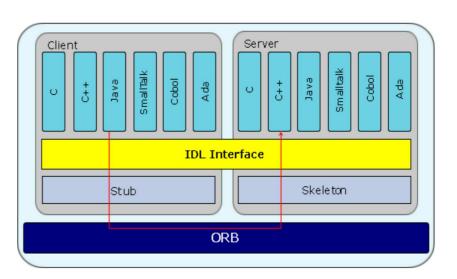
33

CORBA IDL

Language to define CORBA interfaces, independently of a specific programming language

Naturally it is necessary **pass** from the abstract **CORBA level** to concrete **specific languages** (**language mapping**)

CORBA specifies the need of mapping environments
Servant creation is a responsibility of each language mapping



CORBA IDL ENVIRONMENT

CORBA is an environment where we use remote references and do not move objects (static objects) because of the heterogeneity of single deployment environment

Remote references allow to request operations to other components with known CORBA interface

Every object has an interface (coarse granularity)

Interfaces define: attributes, methods, exceptions (attributes accessed through get and set operations) (operations with in or/and out arguments)

The interfaces use multiple inheritance

The **interfaces** can be grouped also within **modules** (for logical aggregations)

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35

OTHER CORBA IDL EXAMPLE

```
module BankAccount {
struct transaction { string data; float amount;};
exception RedException {string message;};
typedef sequence <actions> list_ops;
interface Account {
  float balance(in string cc);
  list_ops bankStatement (in string cc);
  void withdrawal (in string cc, in float amount,
      out float balance) raises RossoException;
  Account accountTwin(); // returns an object };
};
```

Parameters passed by value (CORBA objects by references)

Problem of parameter handling in out and in out

DATA in CORBA IDL

Types in CORBA

Object Reference (references to objects or interfaces)
vs. even with inheritance between CORBA objects

Value (values copy) and Exceptions

Basic values short, long, ushort, ulong, float, double, char, string, boolean, octet, enum, Any

Constructed values Struct, Sequence, Union, Array

Any as general type that contains any type, primitive or from CORBA interface (analyzable during execution)

Object by value (CORBA 3)

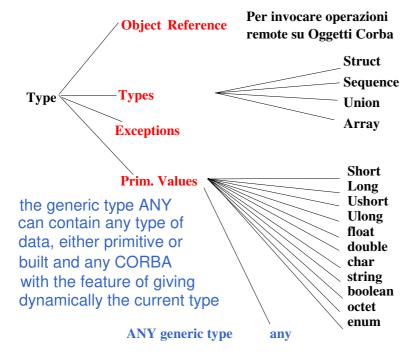
Objects that **cannot** be accessed remotely but only passed **by copy** from an environment to another one overcoming heterogeneity of different environments (no remote reference to them)

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37

TYPES in CORBA IDL

Types in CORBA IDL



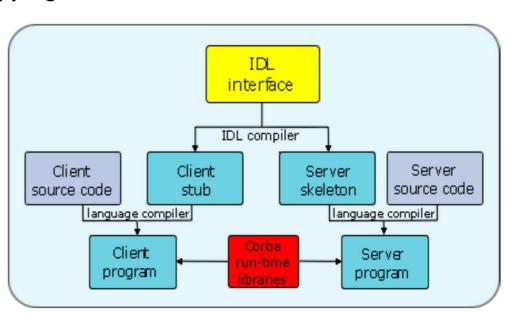
Types of CORBA IDL are than translated into types of different programming languages obtained for different language mapping

Type Object (IDL) represents any type of CORBA object without any information of the specific type

From CORBA IDL to Languages

Tools allows to build from CORBA IDL different components, essential to the project and to execution in **different** language mapping

stub and skeleton + file helper and of other help (holder) + other operations



CORBA Language mapping

CORBA defines

interfaces (with inheritance), exceptions, methods with objects as
parameters of different types and with different modes (in, out,
in out)

Different languages must add **tools**, to harmonize their **structures** to obtain **interface conformance** and guarantee **run-time operations (OO languages must integrate inheritance)**

Strategy for consistency of concrete language types and possibility of integrating with the CORBA model

various transformation functions provided automatically management of types, to put together structures in simple way,

Apart from many other support functions (naming, trading, and suggested development methodologies) usable by user

CORBA vs LANGUAGES: HOLDER

Use of **holders** in JAVA as language where are output parameters for example

```
public final Class BalanceHolder ...
{public float value;
public BalanceHolder() {}
float read() {return value;}
void _write(float value) {this.value = value;}
};
for out and in out parameters (also other helps: helper)
In general, every language must create anything that is necessary
to foster development inside its environment
```

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41

CORBA HELPER

Helper use for Language mapping: in Java functions to

harmonize and treat language types and CORBA types

In Java the CORBA Object type is mapped in org.omg.CORBA.Object

functions of narrow-ing that transform from the CORBA Object type to the one defined inside the interface

functions used for managing transformations from abstract CORBA type for the specific concrete type of interest

implement various utility functions

functions for reading and writing a type on an object stream (associated to CORBA interface), to treat type dynamically during execution, ...

Every language must guarantee interoperability with CORBA

CORBA ENVIRONMENTS AVAILABILITY

Widely used and still rising

Object Broker DEC

ORB HP

DSOM IBM

Orbix IONA

Visibroker Borland

(DOM Facility) DOE Sun Studio Sun

PowerBroker ExperSoft

JacORB, ... Open source tools

Even if the learning curve is high and there is overhead in performances

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43

NOT ONLY C/S: ADVANCED C/S MODELS

Many variant of the Client/Server model

Novel variants

pull (synchronous non blocking)

(the client get afterwards the result, without waiting for it)

push (synchronous non blocking)

(the server gives the result afterwards to the client that do not wait for it) **delegation** waiting for the result **(synchronous non blocking)**

(the delegate waits for the client and gives it the result)

notification for the result

(the delegate notifies the client that a result is arrived)

events (typically asynchronous, so non blocking)

(an event is generated from producer and advertised to consumers) **provisioning**

(other parties can be interested in the call chain, apart from C/S)

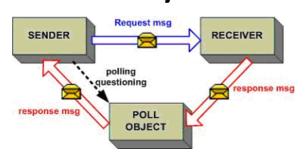
DELEGATION – TO GET THE RESULT...

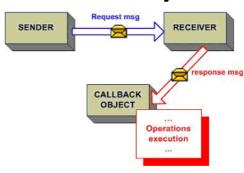
In a synchronous non blocking model, we may have a delegated entity for handling the result

We add a new objects, typically called Poll and Call-Back objects as intermediate entities

Poll Object

Call-Back Object





Used for short operations response time

Even long operations and limited and independent from the client life cycle

We should define specifically the organization in any case

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45

MESSAGE EXCHANGE

Model of MESSAGE exchange

very flexible but primitive, not user friendly

Sometimes the message are only for the synchronization (signals) without any real data communication (carrying no information)

Information exchange: properties

a/ synchronous (no / result)

(the same knowledge of partner) a/ symmetric

(intermediate entity or not) in/ direct

Implementation

non/ blocking (un/blocking of the sender) (non / message queuing) un/buffered (with/without message loss) un/ reliable

Models with multiple receivers or group messages

multicast (MX) and broadcast (BX)

MODES of MESSAGE EXCHANGE

MESSAGE EXCHANGE varies a lot in different systems

Rendez-vous

One to one message exchange that is **synchronous**, **blocking**, **symmetric**, **unbuffered**, **coupled** (more than C/S)

With an intermediate entity (channel, ...)

Message exchange typically **asynchronous**, **non blocking**, asymmetric, **decoupled** (less strict than C/S)

With intermediate entity & receivers group (events, ...)
Message exchange typically asynchronous, non blocking, asymmetric, decoupled and many to many

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47

C/S vs MESSAGE EXCHANGE

Client/Server

Model with strong coupling implies co-presence of interacting parties

Mechanism suitable for high-level and simple communication

Very high level (very suitable for application usage) but not so flexible for differentiated situations, no Multicast (MX) and Broadcast (BX)

Sender/Receiver message exchange

Model with loose (minimal) coupling imposes no **co-presence of interacting parties**Very flexible, primitive, and expressive mechanism, maybe not so easy to use

Very **low level** (and suitable for any system potential usage): many **differentiated modes of usage**, even easy support to any kind of needed communication, e.g., any form of **MX** and **BX**

DE / COUPLING

Communication tools can impose some constraints on the interacting entities (also no imposition)

These constraints can even induce severe limitations on the interaction and force knowledge needs sometimes not required

Different ways of coupling

- space

The interacting entities must know each other and be co-located

- time

The interacting entities must be present at the same time (they should share some intervals of time)

- synchronization

The interacting entities must wait for each other and are subjected to reciprocal limitations and blocks

Decoupling becomes a factor to enable greater flexibility and to leverage the potential distribution of the load in a system

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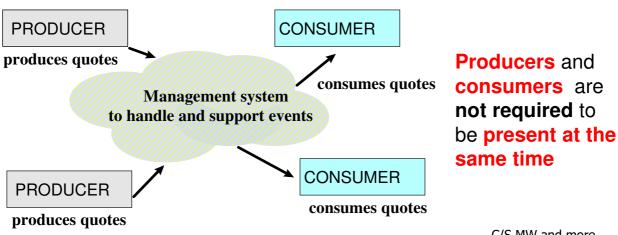
49

EVENT and PUBLISH-SUBSCRIBE

Decoupling between interacting entities

Events are generated by producers, free of doing it when they intend to generate events (publish or PUB) without worrying about delivery

Consumers register their interest in specific events, topics, ... (they have **subscribed SUB**) and the **event support** is in charge of the delivery



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FROM LOCAL EVENTS

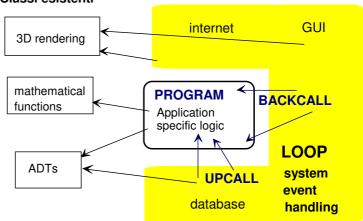
Different model than a synchronous requests of C/S t The Framework tends to reverse the control for low level events

The user process does not wait for result but register with a handling action Example: Windows asks all processes to provide a waiting loop to serve with the it is going to raise to them (and send to them)

When the result is produced the event is raised an the process can go on Classi esistenti

Responses from the framework to the user are called **backcall** or **upcall**

They are similar to an asynchronous event generated by the framework and that application must manage through a **handler function** specified by the user



Available Services and Functions

EVENT SYSTEMS (DISTRIBUTED)

Event systems have been modeled and designed without any locality constraints (no coupling)

The model has its strength in the non-locality of interacting entities only local implementations

Local implementations are not interesting (such as using the sharing on the same node, between producer and consumer), arbitrary, and not meaningful downsizing of the model

Develop a system for events not taking into account the potential decoupling, ...

means to use badly the model properties, one of the worst things we can do to a technology

If you constrain the events to the co-residence and co-presence of interacting entities, you produce a deployment that contrasts with the basic event model

EVENT SYSTEMS: INDICATORS

Event systems have been defined to model **large** systems and scalable ones

Some indicators are core ones

Cost in distributing events (to limit)

Performance (to optimize)

Scalability (to keep high)

Latency (to limit in time)

Pervasivity of provided services (to keep high)

Independent develop and execution (high)

Fault tolerance (maximal possible)

When you implement event systems you start from viability, to mean that you grant that the indicators are scalable, in other words for all distributed implementation indicators keep acceptable values, possibly 'constant'... at least tested

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53

EVOLUTION of EVENTS

Primitive events

some **events** are **on/off signals without any content information** interrupt events and signals triggered by low-level handling functions

Events that carry contents

some contents carry information and one can also **filters** events based **on interest** about **specific information**

RSS as an example, where there is interest only to specified topic and users can register to specific interests

Events with quality - Quality of Service

These **events** can provide **differentiated service for different users:** they can persist and be maintained for all or some users, the delivery can be different depending on receivers, ...

Persistent events: users not online do not lose any event, kept to be delivered a.s.a.p. when they are on

Event priority, e.g., depending on the number of resources devoted to users

PUBLISH-SUBSCRIBE SYSTEMS

PUB-SUB systems are **advanced distributed systems** based on the **event model** and **message exchange** to take the best advantage of the flexibility and the decoupling of interaction to increase **scalability and distribution**

The PUB-SUB model has also many other flexible aspects...

Message filtering based on

topic-based: based on a predefined topic (a specific interest between different channels: such as a specific RSS)

content-based: based on message contents (some keywords or also some more complex relationships)

type-based: based on message type (in case of different message types and a selection done on them)

Quality of Servizio (QoS) over messages

Persistency, Priority, Guarantee of maintenance and duration, ...

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55

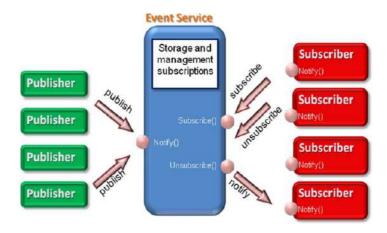
PUBLISH-SUBSCRIBE SYSTEMS

Real PUB-SUB systems support operations for consumer subscription

producers called also **publishers** provide events (they might ask which are current subscribers)

consumers or subscriber that have subscribed must receive events, via a notification

an infrastructure must ensure and grant the operations



DECOUPLED MODELS - TUPLE

TUPLE MODEL for loose and scalable interaction

A general model for communication and synchronization

designed as a shared memory abstraction + communication

A **tuple space** is a set of **structured relationships**, organized as a container for *attributes* and *values* for PUB-SUB

On a tuple space tuples can be deposited / extracted **high-level information** without **causing any interference** or incorrectness

A possible relationship: **message** (**from**, **to**, **body**)

The space is a container of **tuple values** according to the defined attributes (the *attribute types*, here ASCII string)

Tuple values *message*: {Antonio, Giovanni, msg1} {Giovanni, Antonio, msg1} {Antonio, Giovanni, msg2} ...

There are no constraints on tuples that can be deposited and stay in the space forever (almost, it is a model) so **without time** or **space limits**

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57

TUPLE - Linda (Gelernter)

Operations of In e Out on the tuple space

Tuple spaces offer operation always possible and correct for readers (In consumer) and writers (Out producers) competitors with access based on attribute contents

Out inserts one tuple in the space and In extracts one tuple from the space The Out operation emits a tuple on the space available for a match with an In request and the tuple stays there until it is consumed by one corresponding In only

The **In** operation **extracts one matching tuple** from the space, if exists If it dose not exists, the In waits until one is received for the **match that is based on pattern** on the attribute values

In case of match with **multiple tuples**, only one is **non-deterministically extracted**

Out: message (P, Q, text1)
In: message (?from, Q, ?body)

The In may have name of attributes for larger matches

The **In** waits for one tuple with the second attribute the string Q, and give to the consumer the values **from**(=P) e **body**(=text1) of the matching tuple

DECOUPLING TUPLE

Tuple spaces

The communication is rather decoupled and asynchronous

In time

A producer can deposit tuples and go away, and only after a **long time**, the consumer can arrive and get the tuples

In (reciprocal) knowledge (space & synchronization)

The consumers do not know the producers in any way, but only the tuple contents they cannot interfere in any way with production (one in operation extract one tuple, other in-s are queued and wait for their matching tuples and outs operations)

In quality - QoS

Tuple spaces are **persistent** and their requirement is to **maintain deposited tuples without limit (in memory and time)** without any preference for a specific requesting process

Tuple spaces (local implementation) are available to favor local communication well formed and with high level operations

Javaspaces, ...

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59

GROUP COMMUNICATION

Communication within a set of processes

Broadcast e Multicast

How to send general messages either to all currently present processes in the system or to a subset of processes (a group) in the system?

In a **single location** you can easily achieve it (in the same LAN) On different **networks and locations**, you cannot easily achieve it expressive incapacity, excess overhead, lack of QoS, ...

There are some semantic problems to solve in multicast and broadcast

How to cope with the answers (if any)?

- no wait asynchronous operations
- wait for one answer only
- wait for **some answers only** (how many?, how long?)
- wait for all answers (how many? how long? When to stop?)

GROUP COMMUNICATION

IP Broadcast

Broadcast limited and directed (inside local network)

IP Multicast heavier duty and protocol

Multicast for class D addresses

Local Multicast support and ...

Internet uses Internet Group Management IGMP protocol since long ago (RFC 1112 e 2236) to implement local multicast

Often the **protocol could operate only on local subnetworks**, and it is implemented in different and not compatible forms

Multicast (more) global support

A multicast is realized by flooding between networks

a packet can traverse a node only once (node with state) and is sent via any output queue apart from the one where it came in (how long to keep the state?)

Traditional way of routing with simple and low cost (!) policies

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61

IP GROUP COMMUNICATION

One can adopt some basic strategies with mechanisms

For example, we can use an a-priori dimensioning of time-to-live

(TTL) of datagrams (to specify penetration and cost)

TTL=0 local send TTL=1 local to connection

TTL<=32 local to area TTL<=64 local to region

TTL<=128 local to continent TTL>128 global

IP Multicast and the **QoS?**

How can we be sure that the message has been delivered (beyond best-effort semantics)?

There is a limited guarantee on IGMP implementations that is

We do not know if messages were all delivered to all recipients and in which order

GROUP COMMUNICATION

IGMP as an example of local support to Multicast

(RFC 1112 e 2236)

IP multicast allows to send a unique packet to multiple receiver in the same locality, by using class D names to identify a group, not necessarily a local one but spanning a few local networks

The IGMP needs a support from management router

Every local network must hosts at least an IGMP router capable of managing local incoming and outgoing traffic and it controls the group with IGMP messages. It is possible to provide more multicast routers

IGMP v1 considers only two simple messages with C/S approach

IGMPQUERY a **router** periodically verifies the existence of hosts that

answer to a specific IP D address

IGMPREPORT a **node** signals a state change to the router related to the

group (only **join the group** and no **leave**)

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63

IGMP VERSIONING

IGMP v1

Routers are in charge of group management

There is only a **join** message, but no **leave** message from the group in v1 Any router has always an **active** role that require to regularly emit queries: nodes reply to the query to signal their presence or do not reply (problem with nodes that **answer late to the first join query**)

this version requires group operations (only one single report from a node for a single local network)

IGMP v2 (support for join / leave)

The second version consider the capability of nodes to send a message of **explicit leave** (i.e., leave the address group)

Nodes that leave the group must notify the manager

More routers can be in charge of the management

Interference between router is settled with IP numbers order

ROUTING MULTICAST PRINCIPLES

Multicast must employ the least resources as possible during data transmission to receivers

Some assumptions tend to obtain an optimal use of resources and to avoid an excess of bandwidth

- single sender support
- variable number of receivers support (up to n), that can be added or removed dynamically

The main idea is to maximize **sharing**, so to **send only one copy**, instead on N ones, of the same **multicast** message (1 message cost) **instead of different unicast** (N message cost)

Derived from assumptions, protocols identify a central **tree** starting from the sender with **optimal shared paths from sender to current receivers**

The goal is to employ most shared hops as possible from root to leaves

the continuously changing tree must consider only currently active receivers and disregard the ones where there are no currently active receivers

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65

ROUTING MULTICAST (STABLE)

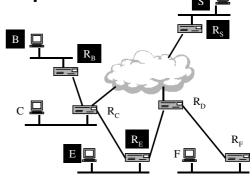
Multicast requires the identification of a (dynamic) tree from sender to receivers for repeated forwarding

the sender is the **root of the tree**, the intermediate routers are the **intermediate** nodes and identify subtrees, the receivers are the **leaf nodes** in the tree

- an open group of nodes with a single sender
- the group membership is dynamic
- leaves are responsible for joining the group
- shared paths optimize bandwidth

The tree is extremely dynamic

Consider the case where an **host S** transmits and **B** and **E** are in the receiver group



MULTICAST: SPANNING TREE

We consider only routers as participants (no nodes) and we want to build a tree from the interconnection graph

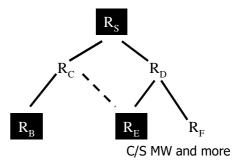
First step (request for leaf identification: root to leaves)

We want to build a tree (a **spanning tree**) that connects root to known leaf nodes, typically by using unicast routing protocol information and **organizing and aggregating paths**

We start sending a **flooding** message towards **every** possible recipient with the main objective of creating a **bone multicast**

The root identifies shortest paths by building it from replies from receivers

some receivers nodes are reached through multiple paths



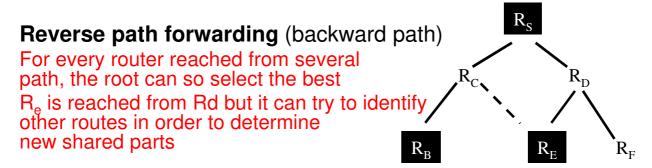
67

MULTICAST: MULTIPLE PATHS

Second step (go back from leaves to root)

Every leaf signals direct **paths** (backwards) and can also **identify new paths** (even not shortest) for going from root to leaves

minimal path messages are sent backward from leaves to root only some paths are selected, other are discarded some shortest path messages from the source are sent back in a larger scope: they are forwarded from leaves on all exit links, except the one where it was coming (to identify other better paths not traversed from root to leaves)



MULTICAST in ACTION

Normal routing: normal routing operation must work continuously while tree identification is ongoing...

Distance Vector

Next hop information must be used (or use poisoned reverse) in order to block too long paths

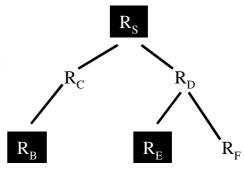
Link State

All shortest path trees must be built for every node and use "tie break" rules to settle conflicts

Reverse Path Broadcast (2 step) for deleting Multiple Paths

Leaves send a broadcast **towards the root** during normal routing operations

The root receive new paths and can reorganize the tree trying to aggregate several sub-paths and produce an optimal tree



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69

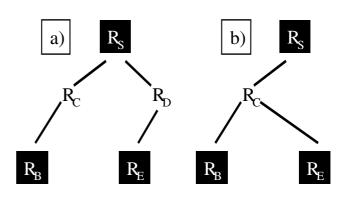
REVERSE PATH BROADCAST

Reverse Path Broadcast allows to choose between different paths to organize the optimal tree, while minimizing the number of sent messages and used bandwidth

With a broadcast from leaves (the **Reverse Path Multicast**) it is possible to **find paths**, **connecting leaves with the root**, **that have not been previously explored**

It is up to the root to choose the best tree organization

Reverse Path Multicasting (RPM) to reorganize the tree (even with a high cost)



MULTICAST: PRUNING and GRAFTING

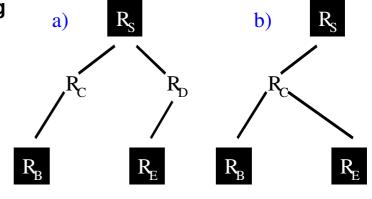
PRUNING and **GRAFT**

routers that have no receivers connected are excluded with 'cut' messages that flows throughout the tree

The tree must be rebuilt in case of any modification

Reverse Path Multicasting (RPM) autonomously done by the leaves to consent PRUNING - from a) to b) and reinserting parts of the tree

GRAFT - from b) to a)



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71

REVERSE PATH MULTICAST

Reverse Path Multicasting from leaves to root (not a broadcast)

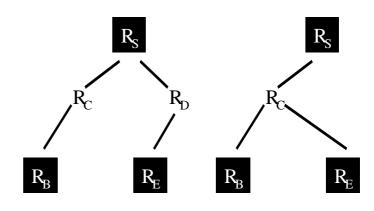
- · used in a lot of multicast protocols
- · keeps the state for communication per-sender, per-group

Networks with no members are **pruned out** from the tree and new ones can reenter the group (**explicit graft** from the bottom) without reorganizing the tree from scratch

The state (software) is kept for a limited and predetermined time

SOFT-STATE

The definition of the RPM time interval is critical



DIFFERENT MULTICAST PROTOCOLS

There are many different **routing multicast** protocols, **incompatible** with each other, even in competition between themselves and supported by different communities

DVMRP (RFC 1075) Distance Vector Multicast Routing Protocol

Employs RPM, based on a modified version of RIP and very used in MBONE (multicast backbone)

Update messages are sent using special paths (tunnel) and using only some nodes

MOSPF (RFC 1584) Multicast Open Shortest Path First Protocol

Extends link-state, suitable for big networks, based on RPM and soft-state It starts from networks map and uses them to calculate shortest path to every single destination

It optimizes the trees and removes not used paths

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73

MANY STANDARD MULTICAST

PIM (RFC 2117) Protocol Independent Multicast Protocol

Uses any unicast protocol in different ways so to suit different systems

Scattered intended when there is a low probability of multiple nodes on the same LAN and Dense where there are many neighbors routers

Scattered: removing the most number of intermediate router to simplify the tree structure

Dense: use of flooding and prune, simplified with regard to DVMRP

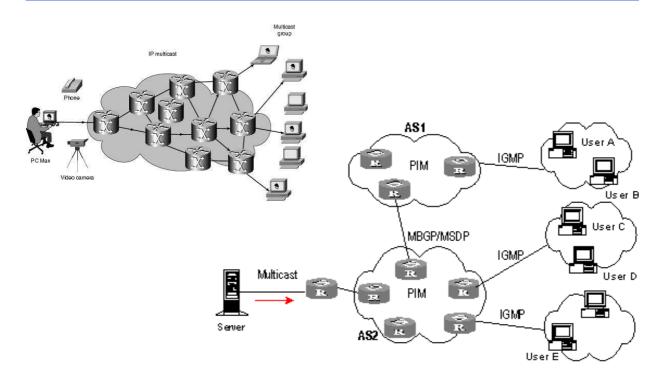
CBT (RFC 2201) Core Based Trees

suitable for an organization based on core routers to choose

Some **nodes are fixed** (core) and **trees are unified** without defining a per-sender or per-group state

It is possible to use sub-optimal tree organizations to avoid reorganizing connection for every multicast reconfiguration

MULTICAST PROTOCOLS



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75

MOM MIDDLEWARE

Message Oriented Middleware (MOM)

Data and code distribution via **message exchange** between **logically separated entities**

Typed & un-typed message exchange with ad-hoc tools both synchronous and asynchronous

- wide autonomy between components
- asynchronous and persistency actions
- handler (broker) with different strategies and QoS
- easy in multicast, broadcast, publish / subscribe

Example: Middleware based on messages and queues MQSeries IBM, MSMQ Microsoft, JMS SUN, OMG DDS, MQTT, RabbitMQ, Active MQ, ...

MOM DEPLOYMENT

The specific deployment and the interconnection graph (OR) is always static (without the need of a name system)

Network overlay model between different applications with specific support in distributed environment

Necessity of high-level Routing (as in ONs, but static)

Data treatment while communicating between different environments

Predefined and static participating entities

Centralized model

MOM with a central node as hub-and-spoke that is responsible of support and pass messages between **different clients**

Distributed model

MOM is located on any client node to form a static ON network, that operate through P2P communication messages between nodes in need of communication

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77

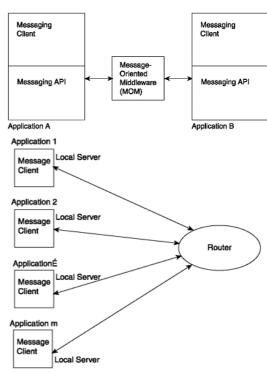
MIDDLEWARE MOM

MOMs provide simple and efficient services

Communication operations available via local ad-hoc API

MOMs put together different nodes and provide services on different fruition nodes arranging queues for the support of every communication

MOMs as integrators use of routers, their interconnection and format conversion



C/S MW and more

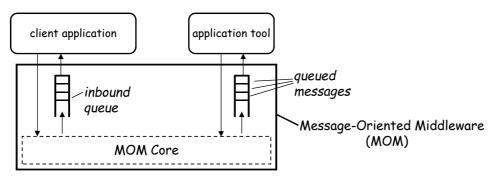
MESSAGE-ORIENTED MIDDLEWARE

MOMs use queues local to interested nodes

Inbound and outbound queues on interested different machines (connected in an univocal way)

Queue managers guarantee the expected operation level and message forwarding

Routing system to connect different queues (as an overlay network for application level routing)



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79

MIDDLEWARE MOM or GLUE

By following a 'Glue' model

MOMs keep together **different autonomous systems** and organize their specific **interconnection**

Relay are **intermediate** entities that allow the implementation to scale and to organize high level **routing**

Message Broker are entities able to support message content transfer between environments with different representations

The MOM operations use not only asynchronous point-topoint messages, but also many-to-many communications

The realization cost must be limited and reduced: the main objective is to fast integrate existent legacy systems

MOM: MQSeries IBM

MOM proposal very popular and supported

Typically, the interconnection graph (routing) is controlled by an always static and inflexible system management (no name servers and no dynamicity)

Application level messages are managed by a **queue** manager

Processes interact through API RPC to put/extract messages from local queues

Transfers are enabled by unidirectional **channels** managed by **Message Channel Agents** that deal with all details (different delivery politics, message type, etc.)

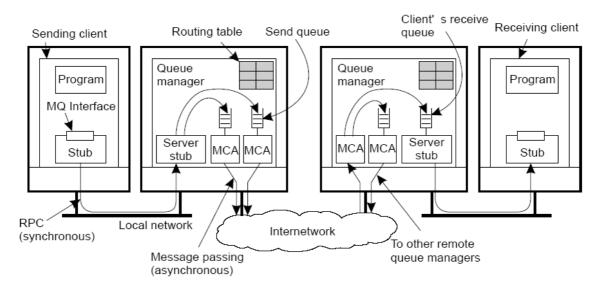
MCA coordination is offered via **primitives** that should enable flexible coordination (different activation policies, duration, maximum allowed cost, state persistence, etc.)

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81

MQSeries IBM – Websphere part

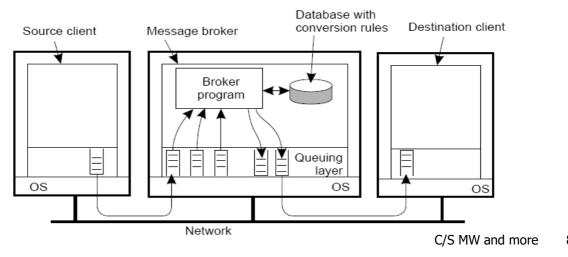
For the deployment, the system administrator defines the appropriate interconnections by using routing tables, at the configuration time



MQSeries IBM: Broker

To achieve the best integration, an MQ Broker can operate on the messages by:

- modifying formats
- organizing routing based on contained information;
- working on application information, to specify action sequence



83