Un' introduzione a sistemi multiagenti basati su logica computazionale

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Scopo del tutorial

- Impossibile in 3 ore
 - essere esaustivi
 - fornire una panoramica completa
- Possibile in 3 ore (obiettivi)
 - Introdurre i sistemi ad agenti intelligenti e la logica (computazionale): cosa e perché
 - Fornire *chiavi di accesso* al settore (con particolare riferimento alla parte dei protocolli e della comunicazione).
 - Presentare, con un esempio di attivita` di ricerca (tratto dal progetto europeo SOCS) alcune delle potenzialita` del settore.

Outline

- **1.** Introduction to agents and their applications
- 2. Agent Architectures
- **3.** Towards Multi Agent Systems (MAS): Agent Communication Languages and Protocols
- 4. Logic programming-based approaches to multi-agent systems: a computational logic model for the description, analysis and verification of global and open Societies Of heterogeneous *ComputeeS* (SOCS)

Part One

Introduction to agents and their applications

What is an (intelligent) Agent?

Fields that inspired the Agent field?

- Artificial Intelligence
 - Agent Intelligence, Micro-aspects of Agents
- Software Engineering
 - Agent as an abstraction
- Distributed Systems and Computer Networks
 - Agent Architectures, Multi-Agent Systems, Coordination
- Game Theory and Economics
 - Negotiation

There are many definitions of agents

Problem-solving agents

function SIMPLE-PROBLEM-SOLVING-AGENT(percept) returns an action static: *seq*, an action sequence, initially empty *state*, some description of the current world state goal, a goal, initially null problem, a problem formulation $state \leftarrow UPDATE-STATE(state, percept)$ if *seq* is empty then do $goal \leftarrow FORMULATE-GOAL(state)$ $problem \leftarrow FORMULATE-PROBLEM(state, goal)$ $seq \leftarrow SEARCH(problem)$ $action \leftarrow FIRST(seq)$ $seq \leftarrow \text{Rest}(seq)$ return action

Agent - Definitions

Russel and Norvig:

"An agent is anything that can be viewed as <u>perceiving</u> its environment through sensors and <u>acting</u> upon that environment through effectors."

Maes, Pattie:

"Autonomous Agents are computational systems that <u>inhabit</u> some complex dynamic environment, <u>sense</u> and <u>act</u> autonomously in this environment, and by doing so <u>realize</u> a set of goals or tasks for which they are designed".

Hayes-Roth:

"Intelligent Agents continuously perform three functions: <u>perception</u> of dynamic conditions in the environment; <u>action</u> to affect conditions in the environment; and <u>reasoning</u> to interpret perceptions, solve problems, draw inferences, and determine actions.

IBM:

"Intelligent agents are software entities that carry out some set of <u>operations on</u> <u>behalf of</u> a user or another program with some degree of <u>independence</u> or <u>autonomy</u>, and in doing so, employ some <u>knowledge</u> or <u>representations</u> of the user's <u>goals</u> or <u>desires</u>"

Weak Notion of Agency

Wooldridge and Jennings:

"An Agent is a piece of hardware or (more commonly) softwarebased computer system that enjoys the following properties:

- <u>Autonomy</u>: agents operate without the direct intervention of humans or others, and have some kind of control over their actions and internal state;
- <u>Pro-activeness</u>: agents do not simply act in response to their environment, they are able to exhibit goal-directed behavior by taking the initiative.
- <u>Reactivity</u>: agents perceive their environment and respond to it in timely fashion to changes that occur in it.
- <u>Social Ability</u>: agents interact with other agents (and possibly humans) via some kind of agent-communication language."

Strong Notion of Agency

Weak Notion in addition to:

- <u>Mobility</u>: the ability of an agent to move around a network
- <u>Veracity</u>: agent will not knowingly communicate false information
- <u>Benevolence</u>: agents do not have conflicting goals and always try to do what is asked of it.
- <u>Rationality</u>: an agent will act in order to achieve its goals and will not act in such a way as to prevent its goals being achieved"

Object-oriented vs. Agent-oriented Programming

- Basic unit:
 - object
- Encapsulates:
 - state
- Communication:
 - Method invocation (client/server)
- Types of message:
 - call (no control)

- Basic unit:
 - agent
- Encapsulates:
 - state + behaviour (can decide actions)...
- Communication:
 - message passing
- Types of message:
 - request, offer, promise, decline, actions (agents can say: no!)

Summary of Agent definitions

- An agent <u>has</u> the <u>weak agent characteristics</u> (autonomy, pro-activity, reactivity and social ability)
- An agent <u>may</u> have the <u>strong agent characteristics</u> (mobility, veracity, benevolence and rationality)
- Generally, an agent <u>acts on behalf</u> another user or entity

What environment?

- Phisical environment?
 - robot, SW/HW agents
 - Partially known and modifiable
 - Phisical low
- Virtual Environmemt?
 - SW agents
 - Designed by humans
 - e.g. Internet
 - Etherogeneous
 - Distributed
 - Dynamic
 - Impredictible
 - Unreliable
 - Open



Many synonyms

- Many synonyms of the term "intelligent agent"
 - Robots
 - Software Agents or Softbots
 - Knowbots
 - Taskbots
 - Userbots
 - Computees
 - ...

Many kinds of Agents

- Interface Agent:
 - Agents interacting with (human) users
- Information Agents:
 - Help users in
 - Find information
 - Gather/collect information
 - Select&Synthesize knowledge based on information
- Mobile Agents
 - Agents that move between runtime systems
- Agents in e-commerce:
 - Perform:
 - Product Brokering
 - Merchant Brokering
 - Negotiation

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Looking at agent systems...

- When the metaphor is appropriate (*customer modelling*, *recommender* systems, *interfaces*)
- When there is a decision to take based on multiple sources, on large amounts of data, and in a dynamic environment (*e-markets, logistics*)
- For complex control tasks, when it is not possible to use a centralized controller and decentralized problem solving is needed (*supply chain management, manufacturing*)
- For simulation of populations of proactive individuals, when a mathematical model is not available (*traffic, games, cinema*)
- When it is necessary to integrate and share knowledge from multiple sources (*databases, business support*)
- Where autonomous problem solving is needed (*electronic trading, space crafts*)
- With high run-time uncertainty, or incomplete or complex information (*telecom services across multiple providers*)

Part Two

Agent Architectures

Overview

Many existing formalisms and frameworks for agent programming

- High-level specification languages
- Idea: to capture the 'essence' of agency through a set of "logical" constructs
- Very expressive abstract frameworks
- Drastically simplified concrete instantiations

Types of Agent Architectures

Deliberative Agent Architectures (BDI and Logic-based):

- Based on symbolic AI
 - Explicit symbolic model of the world
 - Decisision methods:
 - Logical Reasoning
 - Pattern matching
 - Symbolic manipulation

Reactive architectures:

- No central symbolic representation of world
- No complex reasoning
- Reaction to stimolous

(Hybrid architectures)

• Mix of Reactive and Deliberative architecture

Deliberative Architectures

Early systems:

- Planning Systems (STRIPS)
- Symbolic description of World
- Desired goal state
- Set of action descriptions
- → Find a sequence of <u>actions</u> that will achieve <u>goal</u>
- Use very simple planning algorithms
- Very inefficient planning
- → towards BDI architectures

Reactive Architectures

Brooks:

- Intelligent Architectures can be generated <u>without</u> explicit <u>symbolic</u> (AI) <u>representation</u>
- Intelligent behavior can be generated without explicit abstract symbolic reasoning (AI) mechanisms
- Intelligence is an emergent property of certain complex systems
 - Effect of combined components > effect of each component times number of components
- "Real" intelligence is situated in the real world, not in disembodied systems such as theorem provers or expert systems
- Intelligent behavior arises as a result of an agent's interaction with its environment (e.g. Ant colony)

Reactive sub-sumption Architectures



Reactive Architecture Example

Robot's objective:

explore a distant planet (e.g. Mars), and more concretely, collect samples of a particular type of precious rock

- **1.** If detect obstacle then change direction
- 2. If carrying samples and at the base the drop samples
- **3.** If carrying samples and not at the base, go to base
- 4. If detect a sample then pick up sample
- 5. If true then move randomly

Deliberative Architecture: BDI

- BDI aims to model Agents that are *rational* or *intentional*
- The symbols representing the world correspond to *mental attitudes*
- Three cathegories:
 - Informative (knowledge, beliefs, assumptions)
 - Motivational (desires, motivations, goals)
 - Deliberatives (intentions, plans).

BDI Architectures

- **Beliefs:** information about the state of the environment (*informative state*). What an agent think to know now.
- **Desires:** objectives to be accomplished, choice between possible states (*motivational state*). What an agent wishes to become true. Adopted desires are often called Goals.
- Intentions: currently chosen course of action (*deliberative component*). What an agent will try to make true.

An example:

 I believed the tutorial today was at 9:30am and desired not to be late, so I intended to arrive yesterday from Bologna.

BDI formalization

- BDI formalization has 2 main objectives:
 - To build practical systems
 - To build formally verifiable systems
- Building blocks:
 - Interpreter and cycle theory
 - Logics and Semantics



Intentional Notions in Modal Logic

- Classic logic is not suitable for intentional notions.
- **Possible Worlds semantics**
- There are a number of states of affairs, or "worlds"
- Possible worlds may be described in modal logic
- Modal logic can be considered as the logical theory of necessity and possibility
 - The formula A is true if A is true in <u>every</u> world accessible from the current world
 - The formula \$\lapha A\$ is true if A is true in <u>at least one</u> world accessible from the current world

Logic of agent knowledge

The formula A is read as "it is known that A" or "agent knows A"

For group knowledge we have an indexed set of modal operators K₁, ..., K_n for K₁ A is read "agent 1 know A"

Example: $K_1K_2p \land \neg K_2K_1K_2p$

Agent 1 knows that Agent 2 knows p, but Agent 2 doesn't know that Agent 1 knows that Agent 2 knows p

A Logic for BDI

- Agent *i* believes *p* to be true: $B_i p$
- Agent *i* desires that p be true: $D_i p$
- Agent *i* intends to make it so that *p* be true: *I_ip*

Is BDI logic implemented in practical systems?

- The abstract architecture is an *idealization* that faithfully captures the theory, not a *practical* system for rational reasoning
- Modal Logics are used with abstract semantics
- Many implemented systems are *inspired* to BDI concepts
- Solution: some important 'choices of representation' (simplifications) must be made...(PRS)
- Problem: no concrete relationship between theory and system.

Approaches using logic

- Many approaches in literature!!
 - Logic Programming
 - Temporal Logic Concurrent MetateM (Fisher)
 - Situation Calculus ConGolog (De Giacomo, Lespérance, Levesque)
 - Dynamic Logic DyLOG (Patti)
 - Linear logic

→ *Logic Programming based approaches* in the remainder of the tutorial

Why logic programming

- Many agent programming frameworks
 - operational specification is often grounded on logic programming!
- Logic programming useful
 - for the specification of (simplified subsets of) richer programming languages,
 - for agent reasoning,
 - for knowledge manipulation,
 - for verification of properties of agent systems



Thinking component

- Backward reasoning (ALP) combined with forward reasoning (ICs)
- IFF proof-procedure [FK97]: handles IFF definitions and forward integrity constraints (IC)
- Backward reasoning based on based on IFF definitions:
 - it unifies a goal G'
 - with a IFF definition $G \leftrightarrow D_1 \lor \ldots \lor D_n$
 - finding a subgoal $D_1 \lor \ldots \lor D_n$
- Forward reasoning based on IC
 - it matches an observation or atomic goal: O
 - with a condition of an IC O' $\land Q \rightarrow R$
 - finding a new IC (to be true) $Q \rightarrow R$

Example

<u>happens</u> (become-thirsty, T) \rightarrow <u>holds</u> (quench-thirst, [T1, T2]) & T \le T1 \le T2 \le T+10

 $\underline{holds} \text{ (quench-thirst, [T1, T2])} \leftrightarrow \underline{holds} \text{ (drink-soda, [T1, T2]) or} \\ \underline{holds} \text{ (drink-water, [T1, T2])} \\ \underline{holds} \text{ (drink-soda, [T1, T2])} \leftrightarrow \underline{holds} \text{ (have-glass, [T1, T'])} & \\ \underline{holds} \text{ (have-soda, [T'',T2])} & \\ \underline{holds} \text{ (have-soda, [T'',T2])} & \\ \underline{holds} \text{ (have-soda, [T1, T2])} \leftrightarrow \underline{do} \text{ (open-fridge, T1)} & \\ \underline{do} \text{ (get-soda, T2)} & \\ \underline{T1 \leq T2} \\ \underline{holds} \text{ (drink-water, [T1, T2])} \leftrightarrow \\ \underline{holds} \text{ (have-glass, [T1, T'])} & \\ \underline{holds} \text{ (drink, T2)} & \\ \underline{holds} \text{ (have-glass, [T1, T'])} & \\ \\ \underline{do} \text{ (open-tap, T'')} & \\ \\ \underline{do} \text{ (drink, T2)} & \\ \\ \underline{T1 < T'' < T2 \leq T'} \\ \end{array}$

KS-agents vs. BDI

- BDI: uses two languages (modal logic specifications / procedural implementation);
- KS: uses the same language for specification and implementation
The SOCS computee: a computational logic based intelligent agent

- An internal (mental) state;
- A set of *reasoning* capabilities for performing
 - planning,
 - temporal reasoning,
 - identification of preconditions of actions,
 - reactivity, and
 - goal decision;
- A sensing capability;
- A set of formal state transition rules;
- A set of selection functions;
- A cycle theory.

COMPUTEE



Part Three

Multi Agent Systems (MAS): Agent Communication Languages and Protocols

Motivation behind MAS

- To solve problems too large for a centralized agent
- To provide a solution to inherently distributed problems
- To provide solutions where expertise is distributed
- To offer conceptual clarity and simplicity of design

Benefits:

- Faster problem solving
- Flexibility
- Increased reliability
- Different heterogeneity degrees

Cooperative and Self-interested MAS

- Cooperative
 - Agents designed by <u>interdependent</u> designers
 - Agents act for increased good of the system (i.e. MAS)
 - Concerned with increasing the systems performance and not the individual agents
- Self-interested
 - Agents designed by <u>independent</u> designer
 - Agents have their own agenda and motivation
 - Concerned with the benefit of each agent ("individualistic")
- \Rightarrow The latter more realistic in an Internet-setting?

Motivation for Agent Communication and MAS

- Communication is required for cooperation between agents
- Societies can perform tasks no individual agent can
- Autonomy encourages disregard for other agents' internal structure
- Communicating agents need only know a "common language"
- Supports heterogenous agents

A layered architecture

SOCIETIES

PROTOCOLS

ACL LANGUAGE

PLATFORM

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Basic Architecture

Platform

- handle simple objects with no associated semantics
- support communication mechanisms (e.g., RPC) and low-level protocols (e.g., TCP/IP).
- Agent Communication Language (ACL)
 - provides agents with a means to exchange information and knowledge.
 - handles propositions, rules, actions etc..

Protocols

represent the allowed interactions among communicating agents of a society.

Society

intended as a group of agents possibly with roles, common protocols, and laws.

Features of ACLs

- Efficient
 - Few bytes but much meaning, rich semantics for each message
 - Easy-to-use for both machines and humans
- Based on Open Standards
 - Allow agent and agent systems by different vendors to communicate
- Flexible
 - Easy to extend without changing the language, using ontologies
 - Support several syntactic representations
- Have clear non-ambigious semantics and syntax
 - "logic features"
 - Avoid contradictions
- Expressive and High-level
 - Be inspired by natural language

Speech Act Theory and ACLs

- Theory of human communication with language.
 - Consider sentences for their effect on the world
 - A *speech act* is an act carried out using the language
- Several categories of speech acts.
 - Orders, advices, requests, queries, declarations
- Agent Communication Languages use messages.
 - Messages carry speech act from an agent to another
 - A message has *transport slots* (sender, receiver,...)
 - A message has a *type* (request, tell, query..)
 - A message has content slots.

Say What?

- An Agent Communication Language captures:
 - The speaker (sender) and the hearer (receiver) identities
 - The kind of speech act the sender is uttering.
 - Is this enough? ("I request that you frtafs the fgafag")
- Not only words but also the world!
 - There are also things
 - A common description of the world is needed
 - Describing actions, predicates and entities: ontologies

Cosa sono le ontologie

• Filosofia/Computer ScienceAI: area dell'intelligenza artificiale che studia i metodi per rappresentare correttamente l'universo che ci circonda.

Perchè servono in CS?

- Condivisione di conoscenza: per non duplicare sforzi nello sviluppo di sistemi software
- Comunicazione: sia tra agenti software (tra di loro) che tra agenti software e esseri umani

Semantic Web!

Ontogie e Web Semantico

- Possibilità di accesso e acquisizione della conoscenza tramite www
- Costo trascurabile per acquisire basi di conoscenza
- Necessità di organizzare, integrare e interrogare basi di conoscenza
- Necessità di sorgenti di conoscenza facilmente accessibili da macchine e processi automatici
- Necessità di una conoscenza riutilizzabile e condivisibile (in contesti e forme differenti)



Problemi di fondo

- Occorre eliminare la confusione terminologica e concettuale ed individuare le *entità* cui un pacchetto di conoscenza si riferisce.
- Organizzare e rendere esplicito il *significato referenziale* permette di *comprendere* l'informazione.
- 3. Condividere questa *comprensione* facilita il recupero e il riutilizzo della conoscenza tra agenti e in contesti diversi.

ONTOLOGIE



Definizione formale di un dominio di conoscenza

Isolare una parte del mondo e i suoi concetti fondamentali

Enumerare e definire (in modo più o meno formale) i concetti e le relazioni che tra essi sussistono: \rightarrow classi, proprietà, assiomi, individui

Una descrizione strutturata gerarchicamente dei concetti importanti e delle loro proprietà che trovi il consenso di diversi attori interessati a condividerla e utilizzarla.





Speech acts – Types

- Assertives: "It rains"
- Directives: "Close the window"
- Commisives: "I will"
- Expressives: "Excuse me", "congratulations"
- Declaratives: "In name of this city"
- Permissives: "You <u>may</u> shot the door"
- Prohibitives: "You <u>may not</u> shot the door"

Agent Communication Languages

- Two major proposals
 - **KQML** (1993 ~1998)
 - Knowledge Query and Manipulation Language Basis: work by the "Knowledge Sharing Effort" group
 - FIPA ACL (1996 now)

Defined by The Foundation for Intelligent Physical Agents (FIPA)

- Define a number of *communicative actions / performatives*
- Semantics based on *mental states*.

KQML Statement Structure

KQML Statements consists of

- **1.** A performative
- 2. Parameters and context information

General syntax:

(KQML-performative :sender word :receiver word :language word :ontology word :content expression

...)

KQML example

(tell

:sender Agent1
:receiver Agent2
:language KIF
:ontology Blocks-World
:content (AND (Block A)(Block B)(On A B))

(inform

:sender i
:receiver j
:language Prolog
:ontology weather42
:content weather(today,raining)

FIPA ACL

FIPA ACL – competing/extending KQML

- FIPA vs KQML
 - Both are based on speech act
 - Different (richer) set of performatives
 - FIPA has a more formal basis
 - FIPA can describe interaction protocols

What is FIPA?

- The Foundation for Intelligent Physical Agents (FIPA) is a non-profit association.
- FIPA's purpose is to promote the success of emerging agent-based applications, services and equipment.
- FIPA operates through the open international collaboration of member organisations, which are companies and universities active in the agent field.
- URL: <u>http://www.fipa.org/</u>
- Recentemente ha terminato il suo lavoro.

ACL (BDI-based) Semantics

- Mentalistic approaches define ACL semantics in terms of agents' mental state (BDI)
- Semantics based on *mental states*:
 - 1. An intuition given in natural language
 - 2. An expression describing the illocutionary act
 - 3. Pre-conditions for sender and receiver
 - 4. Post-conditions in case of successful receipt
 - 5. Any comments
- The formal semantics of a FIPA communicative act (CA) comprises:
 - What must be true for the sender before sending a CA (feasibility precondition)
 - Which intentions of the sender could be satisfied as a consequence of sending the CA (rational effect)

FIPA ACL semantics for inform

<i, INFORM (j, ϕ) > FP : $B_i \phi$ and not $B_i (B_j \phi \text{ or } B_j \text{ not } \phi)$ RE : $B_j \phi$

- The sender informs the receiver that a given proposition is true.
- The content is a predicate
- The sender believes the content
- The sender wants the receiver to believe it.

FIPA ACL semantics for request

- < Sender, REQUEST (Receiver, a) >
 - FP: FP(a) [Sender/Receiver] and

B_{Sender} Agent (Receiver, a) and

not $B_{\text{Sender}} I_{\text{Receiver}}$ Done(a)

- FP (a) [Sender/Receiver] denotes the part of the FPs which are mental attitudes of the Sender (and do not directly involve the receiver).
- B_{Sender} Agent (Receiver, a) means that Sender believes that Receiver can perform a;
- not B_{Sender} I_{Receiver} Done (a) means that the Sender does not believe that the Receiver intends to perform a.

RE: Done(a)

ACL (BDI-based) Semantics

- Agent Sender should not only be aware of his own mental state, but also have beliefs (in this case, negative) about agent Receiver 's mental state.
- Critics to BDI ACL semantics:
 - in general agents cannot read each other's minds
 - in open societies of heterogeneous agents it is not always possible to rely on agent mental states [Singh98]

ACL "Social" Semantics

- An ACL's formal semantics should better emphasise social agency.
- Communication is inherently public and thus depends on the agent's social context.
- The social approach defines ACL semantics in terms of the social effects of the communicative acts.
- Some questions...
 - Why constrain agents' social acts?
 - Why refer to a particular agent architecture?
 - How to *verify* communication?
 - How to approach *openness* and heterogeneity?

Conclusions on current ACLs

- Agent Communication Languages have a common basis – speech act
- Can all desirable communication primitives be modeled after speech acts? Should they?
- Syntax is well specified, but current research is on describing semantics (versus a social approach)
- Intentional level description: which mental attitudes, what definitions?
- Problems with mental attitudes: from theory to practice
- How can we test an agent's compliance with the ACL?

Interaction Protocols

- Observing a single CA says nothing about the receiver.
- We must move from utterances to conversations: desirable sequences of messages for particular tasks.
- **Protocol: set of interaction rules**
 - what actions each agent can take at each time.
- Formalisms for modeling protocols (e.g. Petri-Nets, finite state machines, AUML diagrams), specify protocols as legal sequences of actions.
- FIPA specifies an IP Library, containig conversation templates

UMTS Provider Competition Protocol

Description of problem

- Automatic Selection of UMTS provider
- Mobile Device automatically negotiates for a price with the possible providers

Market Situation (Fiction Example)





Lowest Bidder wins



Negotiation: Contract-Net

Davis&Smith

Negotiation is a process of improving agreement (reducing inconsistency and uncertainty) on common viewpoint or plans through the exchange of relevant information

- Complex Interaction Protocol
- It embeds policies
- One-to-many IP
 - One manager agent
 - N contractor agents
 - A call for proposals is issued
 - A contractor is selected among proponents

Negotiation for task allocation (Contract Net Protocol)


(AUML) FIPA Contract Net

Protocol



Protocols and Properties

- *Protocols* are used to define the allowed sequences of utterances that agents can exchange
- Many protocols can be used to achieve the same objective (e.g. resource sharing)
- *Properties* are important!!
 - properties of protocols (fairness, guaranteed termination, privacy, ...)
 - properties of participants
 - statically verifiable
 - dynamically verifiable (e.g. compliance)

Protocols and social semantics

- Protocols are over-constrained thus affecting autonomy, heterogeneity, opportunities, exceptions.
- According to Yolum, Singh:

"Participants must be constrained in their interactions only to the extent necessary to carry out the given protocol and no more"

Protocol: set of constraints on the social behaviour (motivations for commitment and committed-based semantics).

Society

A MAS is more than a bunch of Agents

- Functional definition of a society
- Society defined by specifying:
 - roles;
 - rules (allowed actions, communication protocols, social commitments);
 - operations to join and exit the society.

Society

- Society modelling
 - teamwork model, benevolence is presumed;
 - deontic model, based on obligations, authorizations, committments;
 - reactive and evolving/auto-organizing models;
- Consequently, different types of society:
 - open/closed;
 - centralized/decentralized;
 - with common or individual goals.

• Assumptions:

- Members must conform (and agree) to its laws
- Members have a common communication language and ontology w.r.t. communicative acts
- Roles are assigned to agents when they enter a society (and they could change over time)

• These specifications imply:

- a mechanism establishing and enforcing conventions that standardize interactions (Institution).
- the presence of a Social Management Infrastructure.

Soc

New challenges: Logics

- Logics?
 - For prototyping
 - For intelligence (reasoning, goals, consistency)
 - For verification (individuals, interactions)



Why Logic Programming

- Logic programming can be used to bridge the gap between
 - theory (high level specification) and
 - practice (execution model) of agents
- Most research on logic programming-based agents focusses on single aspects of agency (reasoning, updates, anticipation, interaction)
- We show a full-fledged agent model (SOCS) based on logic programming, and a computational model for agent interaction

Verification for open systems

- Guerin & Pitt, 2002: 3 kinds of verification:
 - **1.** verify that an agent will always comply
 - 2. verify compliance by observation
 - **3.** verify protocols' properties
- 1) we need to know the agent behaviour
- 2) is particularly suited for *open societies*
- 3) e.g. termination, e other specific properties.

Conclusions

- Logic useful for
 - modelling & specification
 - operational model ⇒ implementation/prototyping
 - identification and verification of properties
- Computational logic used to tackle several different aspects of agent-based programming
- Theory and practice can work together!
- Formal results from logic programming to multi-agents systems!

Pointers to Agent Research

- Web sites:
 - AgentLink II: <u>http://www.agentlink.org</u>
 - UMBC Agent WEB: <u>http://agents.umbc.edu/</u>
 - Agent Based Systems: http://www.agentbase.com/survey.html
 - Agent Construction Tools: <u>http://www.agentbuilder.com/AgentTools/</u>
- Journals
 - Journal of Autonomous Agents and Multi-Agent Systems
- Conferences and Workshops
 - International Joint Conference on Autonomous Agents and Multi-Agent Systems (AAMAS) – next in New York, deadline: 16 January 2004
 - Past events: ATAL, ICMAS, AA and related WS (LNAI, IEEE, and ACM Press)

Pointers to Computational

- Journals
 - Artificial Intelligence
 - Journal of Logic and Computation
 - Annals of Mathematics and Artificial Intelligence
 - The Knowledge Engineering Review
 - Journal of Group Decision and Negotiation
 - Theory and Practice of Logic Programming
 - Journal of Cooperative Information Systems
- Conferences and Workshops
 - Workshop on Computational Logics in Multi-Agent Systems (CLIMA)

Declarative Agent Languages and Technologies (DALT) – watch AAMAS'04 website

Pointers to MAS

• Surveys on multi-agent systems

[JSW98] N. Jennings, K. Sycara, and M. Wooldridge, A Roadmap of Agent Research and Development. AAMASJ 1998.

[WC00] M. Wooldridge and P. Ciancarini, *Agent-Oriented Software Engineering: The State of the Art.* In Proc. First Int. Workshop on Agent-Oriented Software Engineering, LNCS, 2000

[LMP03] M. Luck, P. McBurney, C. Preist, *Agent Technology Roadmap. 2003*. Available electronically <u>http://www.agentlink.org/roadmap/</u>

Books

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[Woo02] M. Wooldridge, *Introduction to Multi-Agent Systems*. John Wiley & Sons, 2002.

Pointers to Research Groups on Computational Logic and Agents

- **3APL**: Intelligent Systems Group, University of Utrecht, <u>http://www.cs.uu.nl/groups/IS/agents/agents.html</u>
- BOID: http://boid.info/
- **RMIT**: <u>http://www.cs.rmit.edu.au/agents/</u>
- GOLOG: Cognitive Robotics Group, University of Toronto, <u>http://www.cs.toronto.edu/cogrobo/</u>
- IMPACT: University of Maryland, http://www.cs.umd.edu/projects/impact/
- JACK: The Agent Oriented Software Group, http://www.agent-software.com/
- MetateM: Logic and Computation Group, University of Liverpool, <u>http://www.csc.liv.ac.uk/~michael/</u>
- **DESIRE**: <u>http://www.cs.vu.nl/vakgroepen/ai/projects/desire/</u>
- CaseLP: DISI, Università di Genova, http://www.disi.unige.it/index.php?research/ai-mas
- ALIAS: DEIS, Università di Bologna, http://lia.deis.unibo.it/research/ALIAS/
- DyLOG: DI, Università di Torino, http://www.di.unito.it/~alice/
- SOCS, EU Project, <u>http://lia.deis.unibo.it/research/socs</u>
- ALFEBIITE, EU Project, <u>http://www.iis.ee.ic.ac.uk/~alfebiite/</u>
- Dagstuhl seminar 02481 on logic based MAS: http://www.cs.man.ac.uk/~zhangy/dagstuhl/