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# Evolutionary computation

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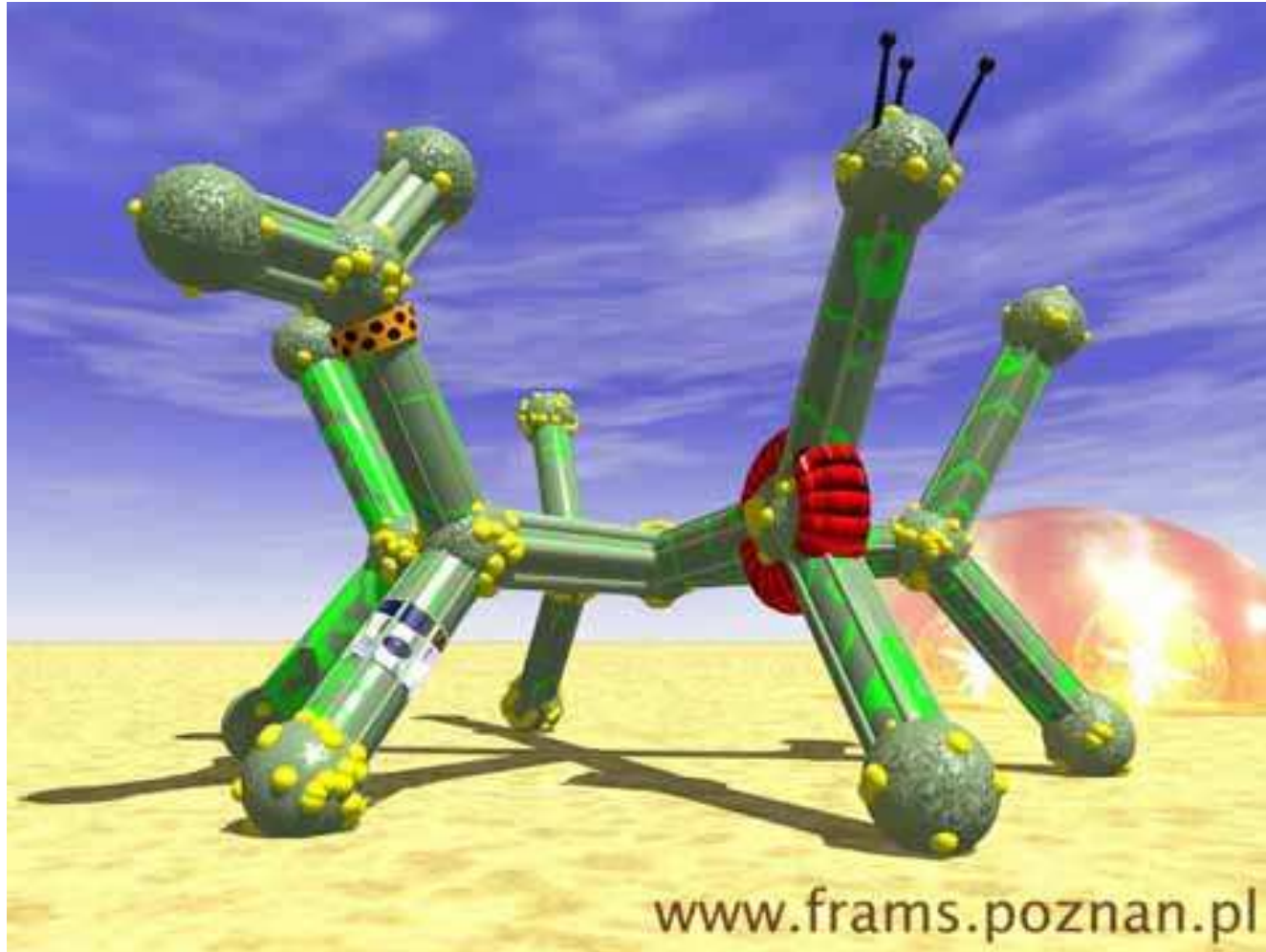
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# Evolutionary Computation

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# Evolutionary Computation

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Inspiring principle: theory of **natural selection**

“Species face the problem of searching for beneficial adaptations to the environment. The *knowledge* that each species has gained is embodied in the makeup of the chromosomes of its members.” (Davis, *Genetic Algorithms and Simulated Annealing*, 1987)

Example: rabbits...

# Evolutionary Computation

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Evolutionary Computation (EC) encompasses:

- Genetic Algorithms
- Genetic Programming
- Evolution Strategies
- Estimation of Distribution Algorithms

# Objectives

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- Problem solving
- Optimization
- Adaptive systems design
- Simulation

# Some applications

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- ▷ System design (e.g., airplanes, electronic circuits, mechanical elements)
- ▷ Neural network training (e.g., robotics)
- ▷ Signal processing (e.g., artificial vision)
- ▷ Optimization (discrete and continuous)

# More applications

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- ▷ Time series analysis and forecasting (e.g., financial forecasting)
- ▷ Artificial Life (e.g., cellular automata, analysis of complex adaptive systems)
- ▷ Games (e.g., Prisoner's Dilemma)

Challenge: find a problem where EC has NOT been applied!

# Genetic Algorithms

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## The Metaphor

NATURAL EVOLUTION

ARTIFICIAL SYSTEMS

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Individual

↔

A possible solution

Fitness

↔

Quality

Environment

↔

Problem



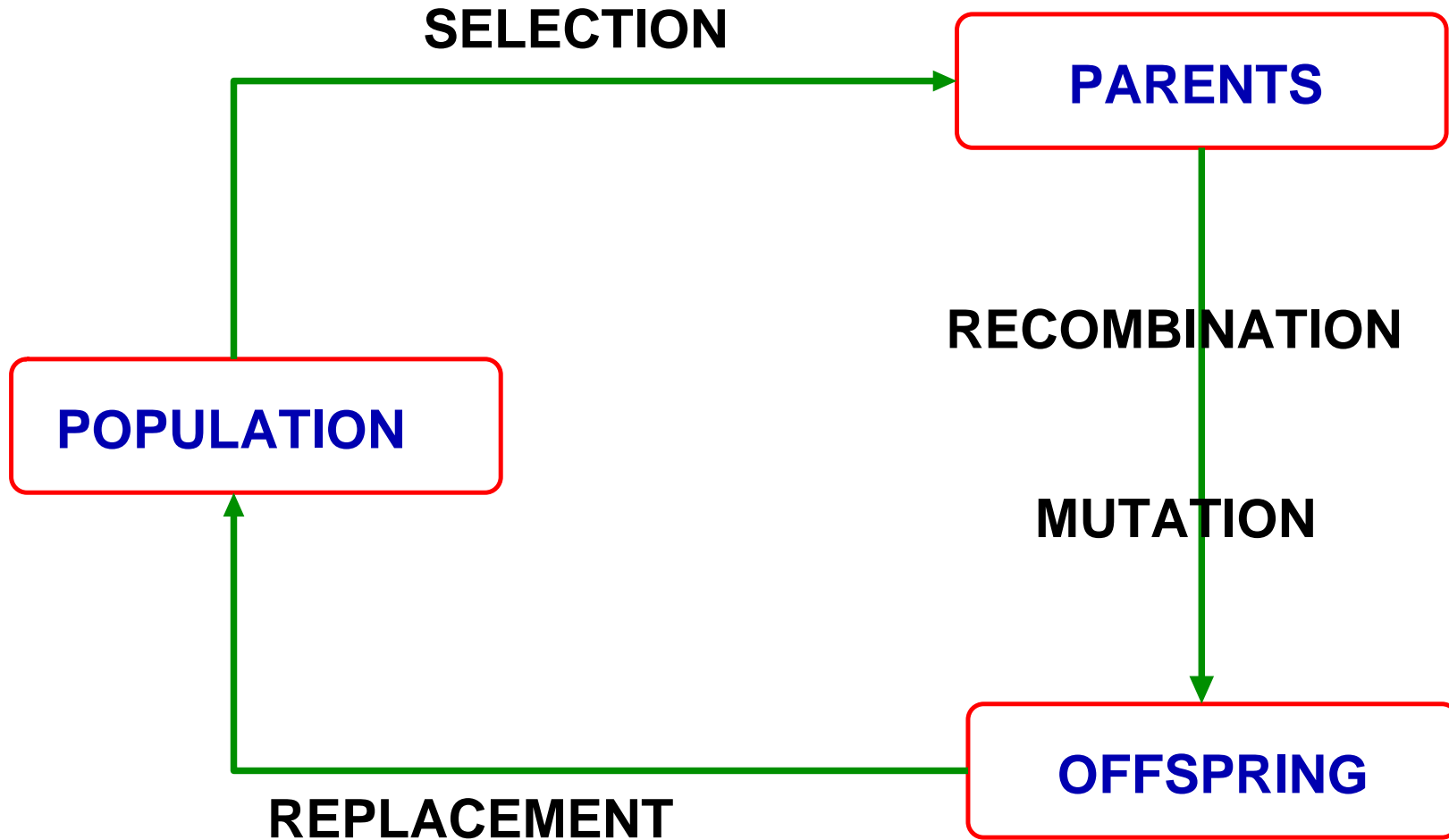
# A bit of terminology

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- A **population** is the set of individuals (solutions)
- Individuals are also called **genotypes** or **chromosomes** (if one solution  $\leftrightarrow$  one chromosome)
- Chromosomes are made of units called **genes**
- The domain of values of a gene is composed of **alleles** (e.g., a binary variable/gene has two alleles)

# The Evolutionary Cycle

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# Genetic operators

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- Mutation
- Recombination
- Selection
- Replacement/insertion

# Genetic operators

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- ▷ EC algorithms define a basic computational procedure which uses the genetic operators.
- ▷ The definition of the genetic operators specifies the actual algorithm.
- ▷ The definition of the genetic operators depends upon the problem at hand.

# Genetic Algorithms

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Developed by John Holland (early '70) with the aim of:

- Understand adaptive processes of natural systems
- Design robust (software) artificial systems

# Simple Genetic Algorithm

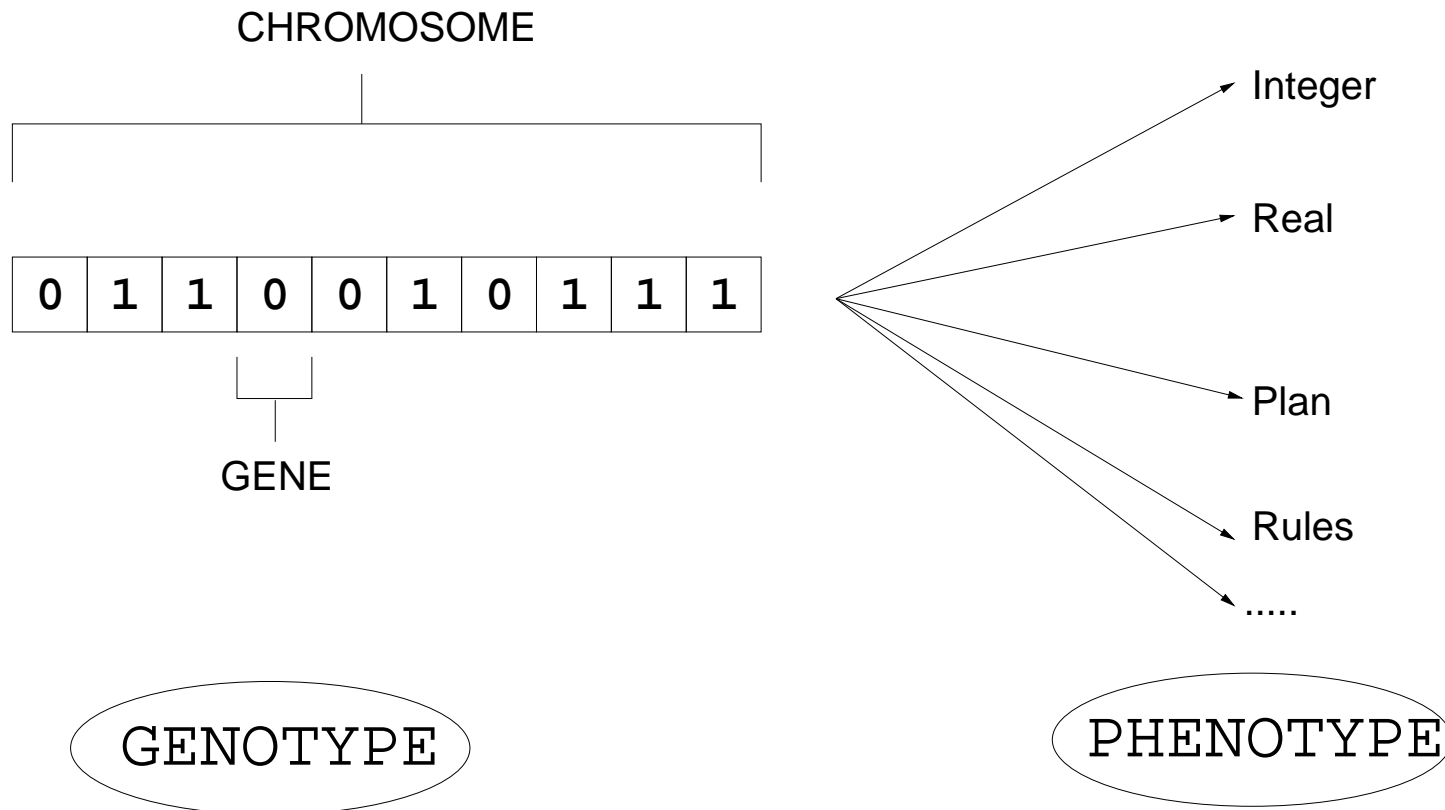
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- Derived from the natural metaphor
- Very simple model
- 'Programming oriented'

You can take it as a first step toward evolutionary algorithms in general

# Simple Genetic Algorithm

Solutions are coded as **bit strings**



# Example

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Optimization of a function of integer variable  $x \in [0, 100]$ :

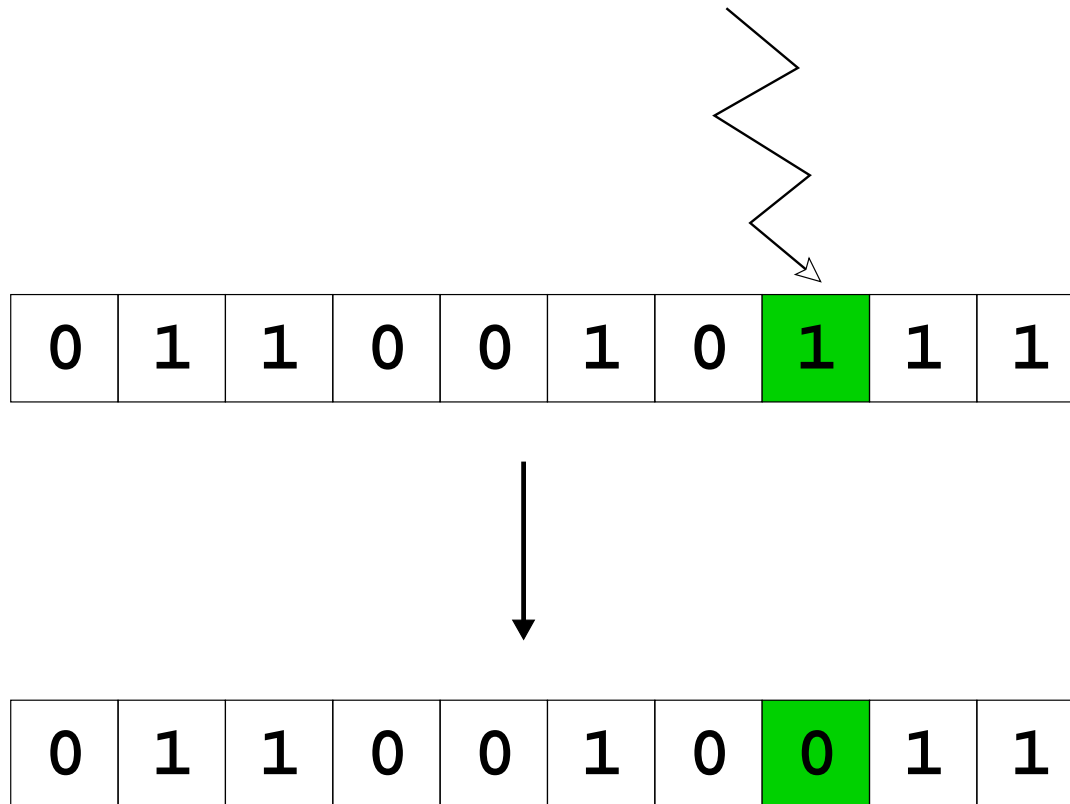
- binary coding  $\rightarrow$  string of 7 bit
- 4 bits per digit  $\rightarrow$  string of 12 bit



# Genetic operators (1)

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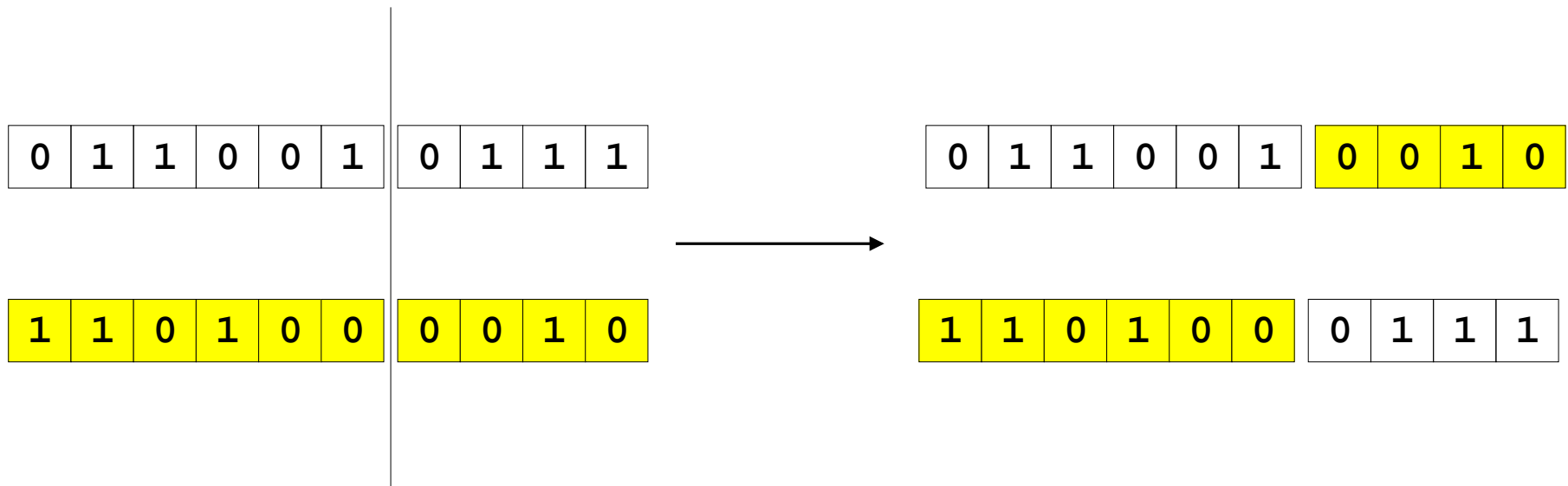
**Mutation:** each gene has probability  $p_M$  of being modified ('flipped')



# Genetic operators (2)

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**Crossover:** cross-combination of two chromosomes  
(loosely resembling human crossover)



# Genetic operators (3)

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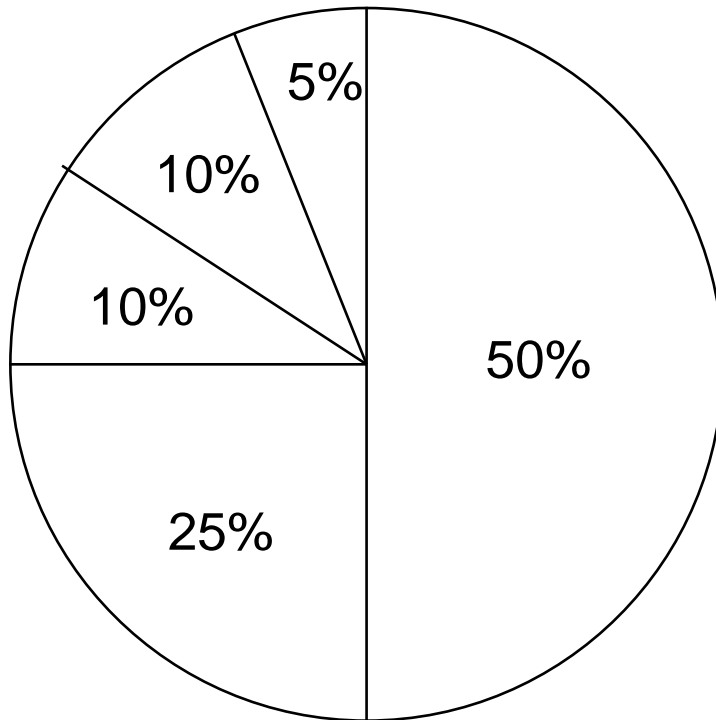
**Selection** acts in the choice of parents and produces the *mating pool*.

→ **Proportional selection**: the probability for an individual to be chosen is proportional to its fitness.

# Genetic operators (3)

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***Roulette wheel***



$I_1$	50
$I_2$	25
$I_3$	10
$I_4$	10
$I_5$	5

# Genetic operators (4)

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**Generational replacement:** The new generation replaces entirely the old one.

- Advantage: very simple, computationally not (extremely) expensive, easier theoretical analysis.
- Disadvantage: we could lose good solutions

# High-level algorithm

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Initialize Population

Evaluate Population

**while** Termination conditions not met **do**

**while** New population not completed **do**

        Select two parents for mating

        Apply crossover

        Apply mutation to each new individual

**end while**

    Population  $\leftarrow$  New population

    Evaluate Population

**end while**

# Termination conditions

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The basic question is: **when to stop?**

- Execution time limit reached
- We are satisfied with the solution(s) obtained
- Stagnation (limit: the population converged to the same individual)

# Simple Genetic Algorithm

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**Initialize Population**{ $N_{pop}$  individuals  $X_1, \dots, X_{N_{pop}}$ }

**for**  $i = 1$  to  $N_{pop}$  **do**

$X_i \leftarrow \text{InitialSolution}()$  {e.g., random}

**end for**

**Evaluate Population**{Individual  $X_i$  has fitness  $F_i$ }

**for**  $i = 1$  to  $N_{pop}$  **do**

$F_i \leftarrow \text{Eval}(X_i)$

**end for**



# Simple Genetic Algorithm

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**Select parents:**  $G_1, G_2$  {Roulette wheel selection}

$lung \leftarrow 0$

**for**  $i = 1$  to  $N_{pop}$  **do** {all fitness values are summed up}

$lung \leftarrow lung + F_i$

**end for**

**for**  $m = 1$  to 2 **do**

$r \leftarrow \text{Random}(0, lung); sum \leftarrow 0; i \leftarrow 1$

**while**  $i < N_{pop}$  AND  $sum < r$  **do**

$sum \leftarrow sum + F_i; i \leftarrow i + 1$

**end while**

$G_m \leftarrow X_i$

**end for**

# Simple Genetic Algorithm

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**Apply crossover:** from  $G_1, G_2$  we get  $G'_1, G'_2$

$r \leftarrow \text{Random}(1, l_{\text{chromosome}})$  {crossover point}

**for**  $i = 1$  to  $r - 1$  **do**

$G'_1[i] \leftarrow G_1[i]$

$G'_2[i] \leftarrow G_2[i]$

**end for**

**for**  $i = r$  to  $l_{\text{chromosome}}$  **do**

$G'_1[i] \leftarrow G_2[i]$

$G'_2[i] \leftarrow G_1[i]$

**end for**

# Simple Genetic Algorithm

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**Apply mutation** to individual  $X$

**for**  $i = 1$  to  $l_{chromosome}$  **do**

$r \leftarrow \text{Random}(0,1)$

**if**  $r \leq p_M$  **then**

    Complement  $X[i]$

**end if**

**end for**

# SGA: Example

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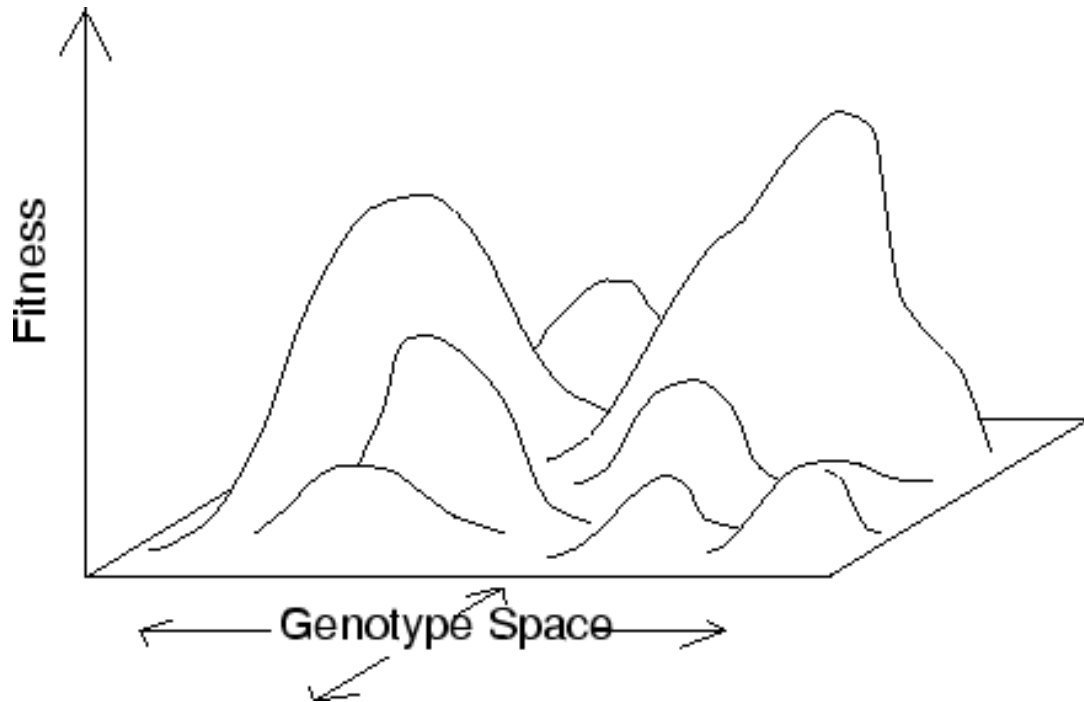
Maximization of a real function

Taken from: <http://www.evonet.polytechnique.fr/CIRCUS2/>

# Fitness Landscape

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Representation of the space of all possible genotypes, along with their fitness.



# Fitness Landscape

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## Caution!

- Different landscapes for different operators
- In many cases fitness landscapes are *dynamic*
- Landscape ‘intuition’ might be misleading
- Use of term *local optimum* used and abused everywhere

# Why does it work?

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Intuition:

- Crossover combines good parts from good solutions (but it might also destroy... sometimes)
- Mutation introduces diversity
- Selection drives the population toward high fitness

# SGA: pros and cons

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## Pros:

- Extremely simple
- General purpose
- Theoretical models

## Cons:

- Coding
- Too simple genetic operators



# A recipe

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The ingredients to prepare a GA:

- Solution coding (e.g., bit strings, programs, arrays of real variables, etc.)
- Define a way of evaluating solutions (e.g., objective function value, result of a program, behavior of a system, etc.)
- Define recombination operators (*crossover*, *mutation*)
- Define the selection and replacement/insertion mechanisms

# Toward *less simple* GA

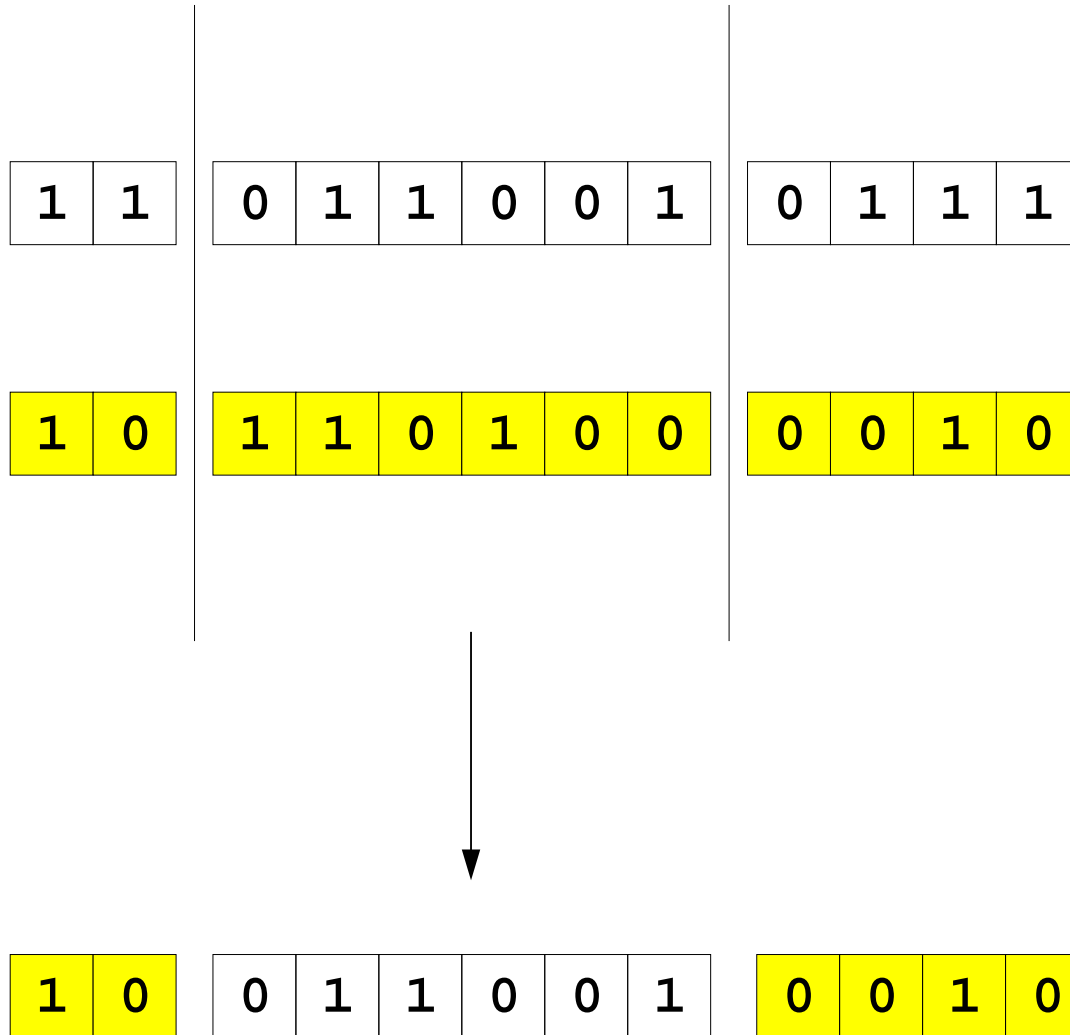
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## Recombination:

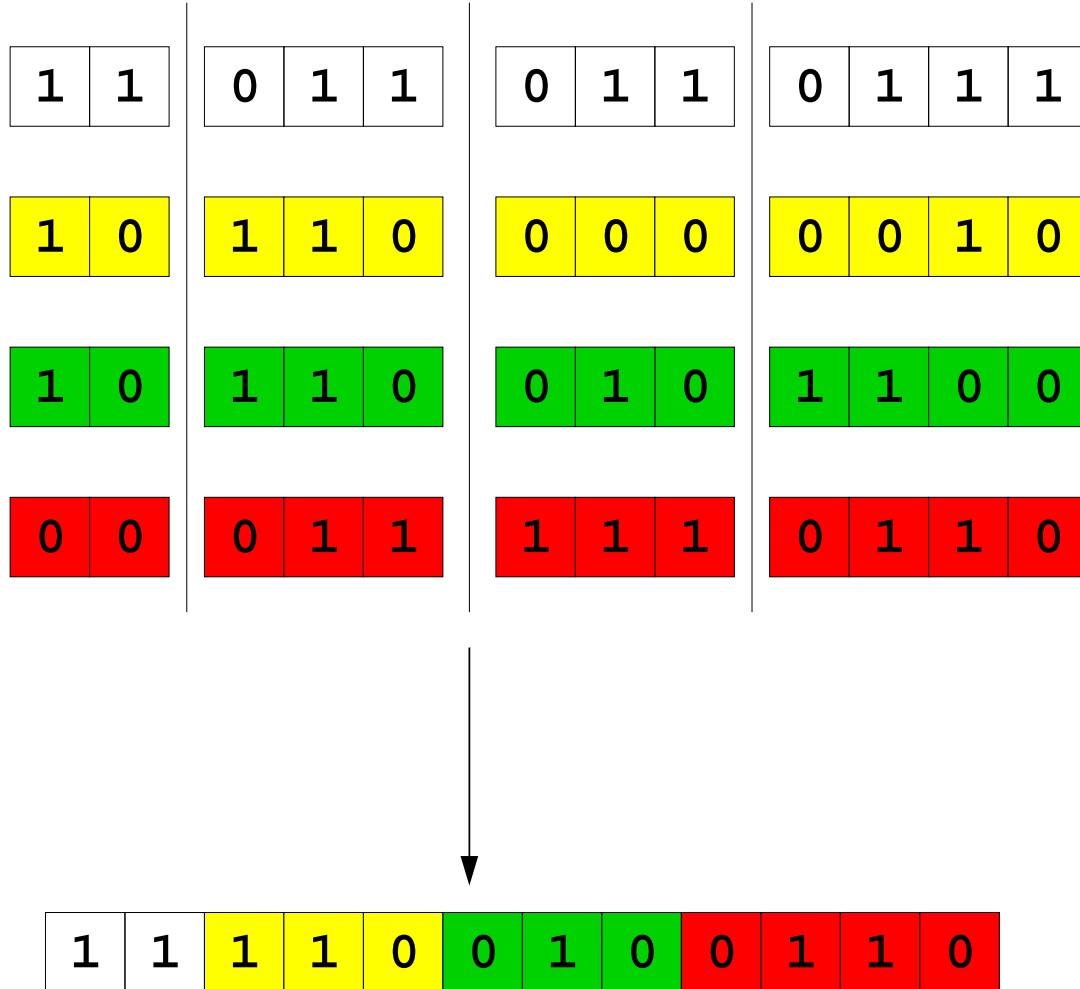
- *Multi-point crossover* (recombination of more than 2 “pieces” of chromosomes)
- *Multi-parent crossover* (an individual is generated by more than 2 parents)
- *Uniform crossover* (children created by randomly shuffling the parent variables at each site)

# Multi-point crossover

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# Multi-parent crossover



# Toward *less simple* GA

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## Mutation:

- Learning applied to modify the chromosome
- In optimization, hill-climbing or more complex local search algorithms can be applied

Interesting topic: Evolution & Learning,

[www.cogs.susx.ac.uk/users/ezequiel/alife-page/evolearn.html](http://www.cogs.susx.ac.uk/users/ezequiel/alife-page/evolearn.html)

# Toward *less simple* GA

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## Selection:

- Different probability distribution (e.g., probability distribution based on the *ranking* of individuals)
- *Tournament Selection* (iteratively pick two or more individuals and put in the *mating pool* the fittest)

# Ex: real valued variables

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- Solution:  $x \in [a, b]$ ,  $a, b \in \mathbb{R}$
- Mutation: random perturbation  $x \rightarrow x \pm \delta$ , accepted if  $x \pm \delta \in [a, b]$
- Crossover: linear combination  $z = \lambda_1 x + \lambda_2 y$ , with  $\lambda_1, \lambda_2$  such that  $a \leq z \leq b$ .

# Example: permutations

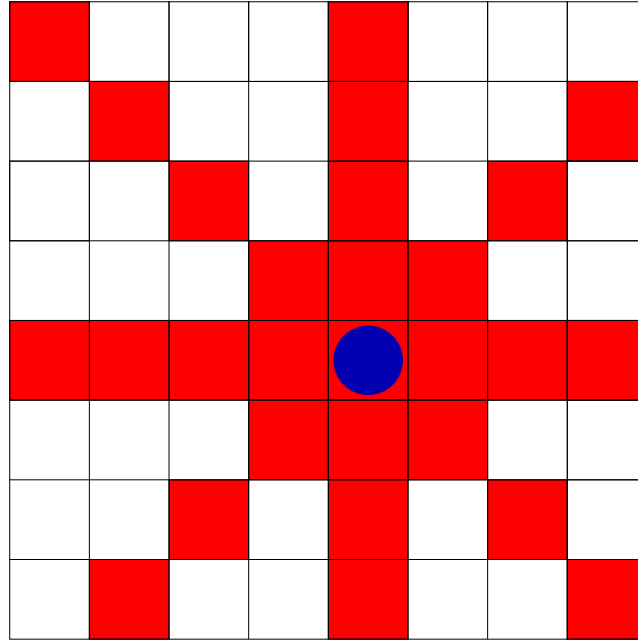
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- Solution:  $x = (x_1, x_2, \dots, x_n)$  is a permutation of  $(1, 2, \dots, n)$
- Mutation: random exchange of two elements in the  $n$ -ple
- Crossover: like 2-point crossover, but avoiding value repetition (see next example).



# Eight Queens

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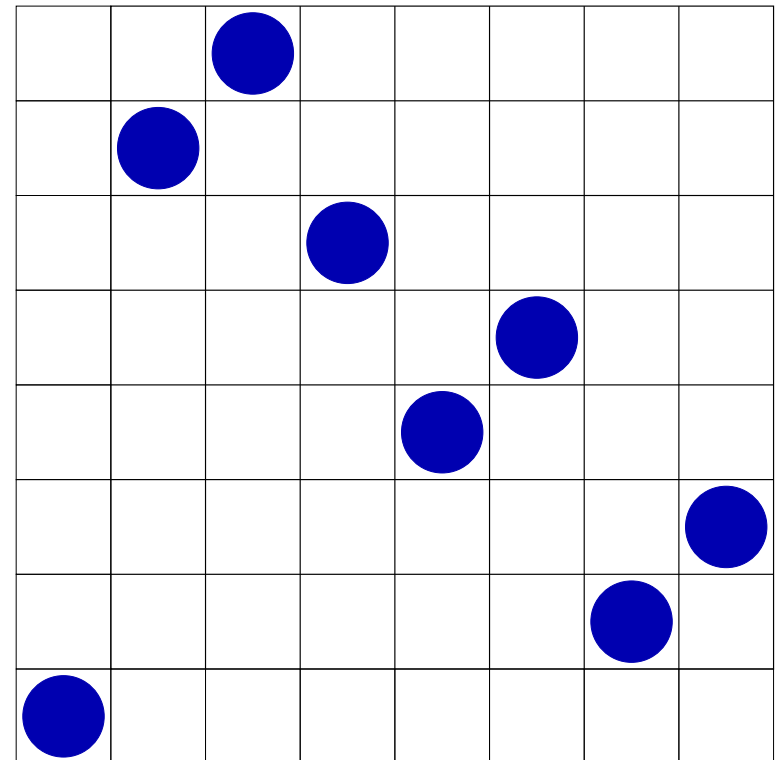


Place 8 queens on a  $8 \times 8$  chessboard in such a way that the queens cannot attack each other.

# Eight Queens

Genotype: a permutation of the numbers 1 through 8

3	2	4	6	5	8	7	1
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# Eight Queens

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Mutation: exchanging two numbers

1	2	1	3	5	4	8	7
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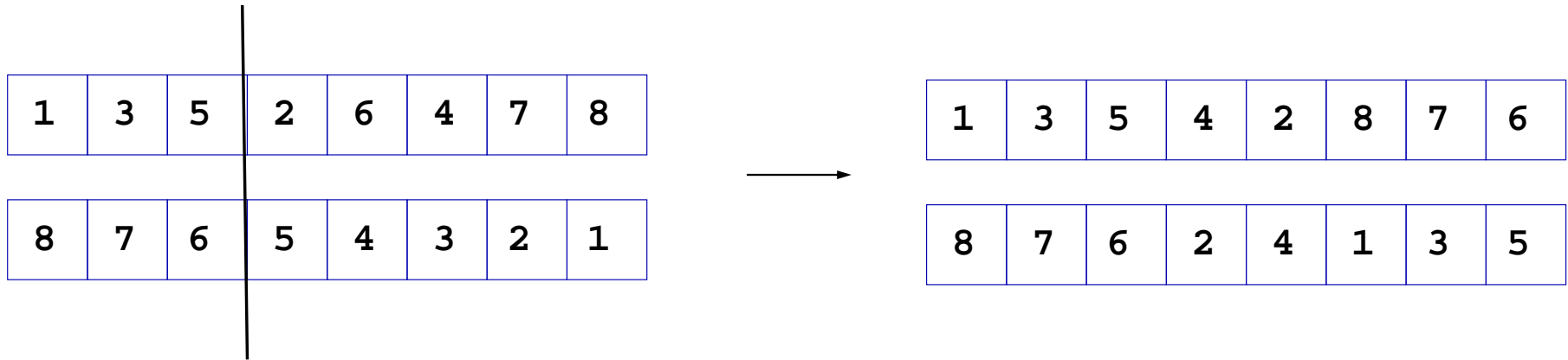


1	2	4	3	5	1	8	7
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# Eight Queens

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Crossover: combining two parents



# Eight Queens

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Fitness: penalty of a queen is the number of queens it can check.

The fitness of the configuration is the sum of the single penalties.

# Example

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## Traveling Salesman Problem

Taken from:

[http://ouray.cudenver.edu/~da0todd/neural/third\\_homework/dave/test/TSP\\_Genetic\\_Algorithm.htm](http://ouray.cudenver.edu/~da0todd/neural/third_homework/dave/test/TSP_Genetic_Algorithm.htm)

# Mondriaan Art

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Mondriaan Art

Taken from: <http://www.evonet.polytechnique.fr/CIRCUS2/>

# Genetic Programming

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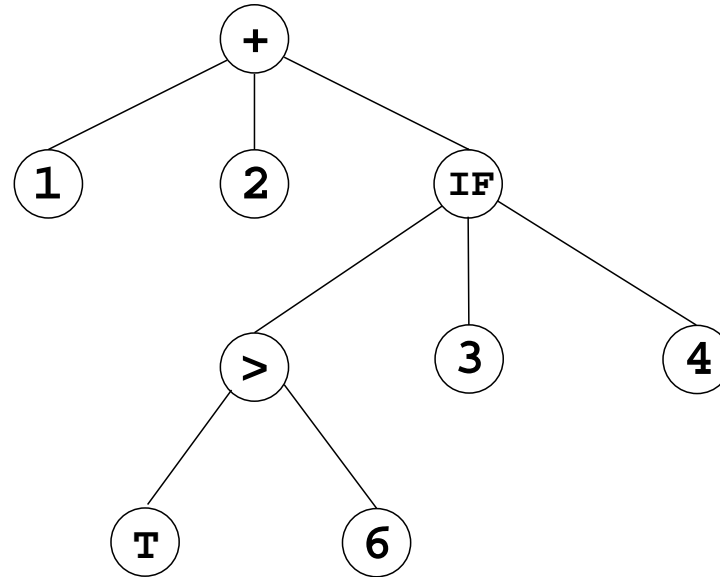
- Can be seen as a ‘variant’ of GA: individuals are **programs**
- Used to build programs that solve the problem at hand (⇒ specialized programs)
- Extended to *automatic design* in general (e.g., controllers and electronic circuits)



# Genetic Programming

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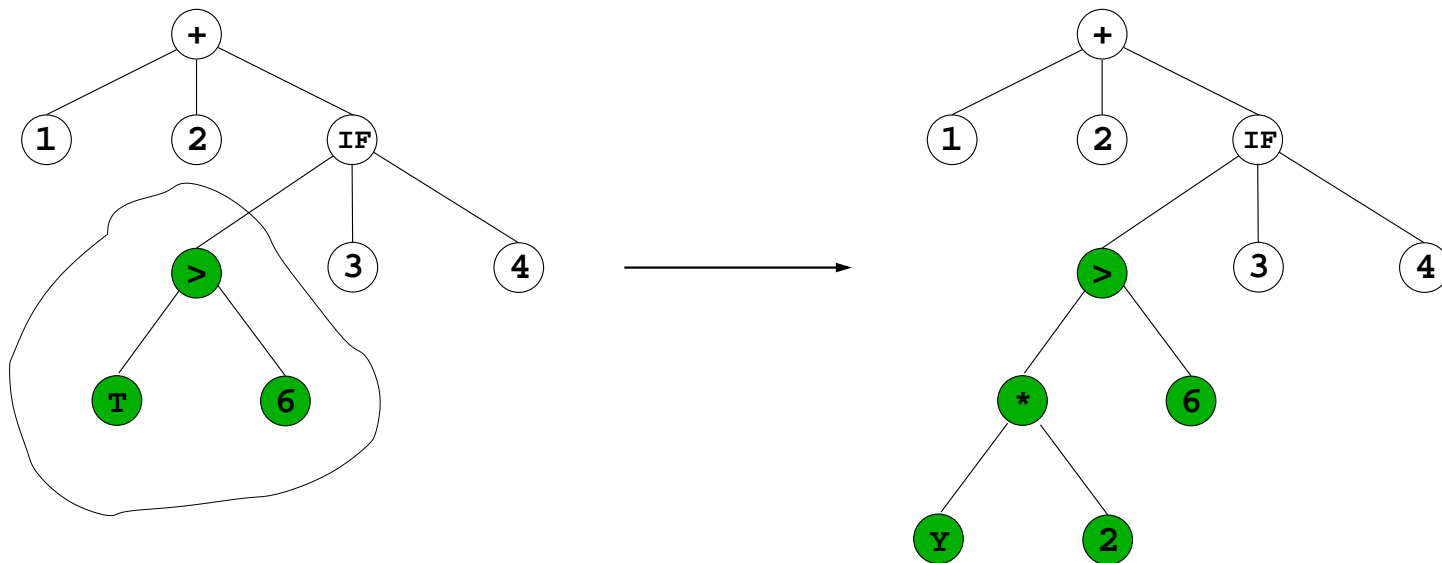
Individuals are *trees* which encode programs.



Fitness given by the evaluation of the program “behavior”  
(based upon some defined criteria)

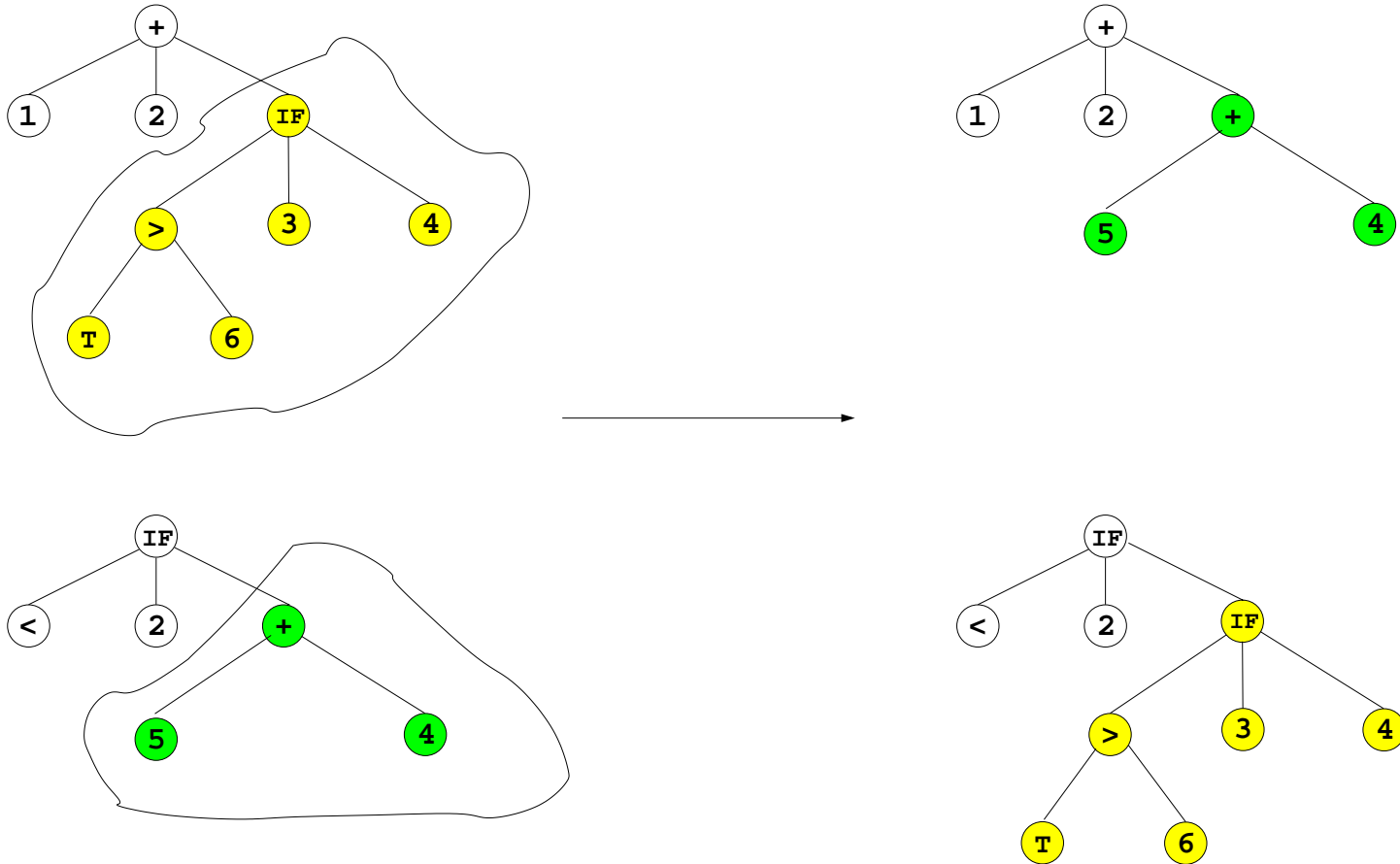
# Operators

**Mutation:** Random selection of a subtree which is substituted by a *well formed* random generated subtree



# Operators

**Crossover:** Exchange two randomly picked subtrees.



# Operators

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## Selection and replacement

Fitness is evaluated depending on the application.

- For *assembler worms* the fitness can be the memory they occupied.
- For controllers, the fitness can be the percentage of correct actions

# The realm of GP

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- *Black art* problems. E.g., automated synthesis of analog electrical circuits, controllers, antennas, and other areas of design
- *Programming the unprogrammable*, involving the automatic creation of computer programs for unconventional computing devices. E.g., cellular automata, parallel systems, multi-agent systems, etc.

# Coevolution

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Species evolve in the same environment

→ ***dynamic*** environment

Two kinds:

- Competitive
- Cooperative

# Competitive Coevolution

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- ▷ Species evolve trying to face each other
  - E.g., prey/predator, herbivore/plants.

Applications: ALU design for Cray computer, (pseudo-)random number generator.

# Cooperative Coevolution

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▷ Species evolve complementary capabilities to survive in their environment

● E.g., host/parasite.

Applications: 'niche' genetic algorithms for *multi-criteria* optimization.



# Some references

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- M.Mitchell. *Genetic Algorithms*. MIT Press, 1999.
- Z.Michalewicz. *Genetic Algorithms + Data Structures = Evolution Programs*, Springer, 1992.
- D.E.Golberg. *Genetic Algorithms in Search, Optimization and Machine Learning*. Addison-Wesley, 1989.
- W.B.Langdon, R.Poli. *Foundations of Genetic Programming*. Springer, 2001.

# On the Internet

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- EvoNet: <http://www.evonet.polytechnique.fr/>
- [www.genetic-programming.com](http://www.genetic-programming.com)
- GALib <http://lancet.mit.edu/ga/>
- <http://www.aic.nrl.navy.mil/galist/>
- [www.isgec.org](http://www.isgec.org)